On Contact Topology, Symplectic Field Theory and the PDE That Unites Them



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How are the following related?

Problem 1 (dynamics):

If $H(q_1, p_1, \ldots, q_n, p_n)$ is a time-independent Hamiltonian and $H^{-1}(c)$ is convex, does

$$\dot{q}_j = \frac{\partial H}{\partial p_j}, \qquad \dot{p}_j = -\frac{\partial H}{\partial q_j}$$

have a periodic orbit in $H^{-1}(c)$?

Problem 2 (topology):
Is a given closed manifold M the boundary of any compact manifold W?
How unique is W?

Problem 3 (complex geometry / PDE): Given a Riemann surface Σ and complex manifold W, what is the space of holomorphic maps $\Sigma \rightarrow W$? (Finite dimensional? Smooth? Compact?)

Problem 4 (mathematical physics): *How trivial is my TQFT?* **Theorem** (Rabinowitz-Weinstein '78). Every star-shaped hypersurface in \mathbb{R}^{2n} admits a periodic orbit.



Definition. A symplectic structure on a 2ndimensional manifold W is a system of local coordinate systems $(q_1, p_1, \ldots, q_n, p_n)$ in which Hamilton's equations are invariant. It carries a natural volume form:

 $dp_1 dq_1 \dots dp_n dq_n$.

 ∂W is **convex** if it is transverse to a vector field Y that *dilates* the symplectic structure.

$M := \partial W$ convex \rightsquigarrow contact structure

$\xi \subset TM,$

a field of tangent hyperplanes that are "locally twisted" (*maximally nonintegrable*),



and transverse to the **Reeb** (i.e. Hamiltonian) vector field.

Example: $T^3 := S^1 \times S^1 \times S^1$



= boundary of $T^2 \times \mathbb{D} = D^*T^2 \subset T^*T^2$.

Some hard problems in contact topology

- 1. Classification of contact structures: given ξ_1, ξ_2 on M, is there a diffeomorphism $\varphi : M \to M$ mapping ξ_1 to ξ_2 ?
- Weinstein conjecture: Every Reeb vector field on every closed contact manifold has a periodic orbit?
- 3. Partial orders: say $(M_-, \xi_-) \prec (M_+, \xi_+)$ if there is a (symplectic, exact or Stein) cobordism between them.



When is $(M_-, \xi_-) \prec (M_+, \xi_+)$? When is $\emptyset \prec (M, \xi)$? (Is it *fillable*?)

Overtwisted vs. tight

Theorem (Eliashberg '89). If ξ_1 and ξ_2 are both overtwisted, then $(M, \xi_1) \cong (M, \xi_2) \Leftrightarrow \xi_1$ and ξ_2 are homotopic.

"Overtwisted contact structures are flexible."



Theorem (Gromov '85 and Eliashberg '89). $\xi \text{ overtwisted} \Rightarrow (M, \xi) \text{ not fillable.}$

Non-overtwisted contact structures are called **"tight"**.

They are not fully understood.

Conjecture. Suppose $(M,\xi) \xrightarrow{contact surgery} (M',\xi')$. Then (M,ξ) tight $\Rightarrow (M',\xi')$ tight.

Surgery \rightsquigarrow handle attaching cobordism:



 $\partial(([0,1] \times M) \cup (\mathbb{D} \times \mathbb{D})) = -M \sqcup M'$

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Recent results: \exists "degrees of tightness".

Theorem (Latschev-W. 2010). There exists a numerical contact invariant $AT(M,\xi) \in \mathbb{N} \cup \{0,\infty\}$ such that:

- $(M_-,\xi_-) \prec (M_+,\xi_+) \Rightarrow$ $\mathsf{AT}(M_{-},\xi_{-}) \leq \mathsf{AT}(M_{+},\xi_{+})$
- $AT(M,\xi) = 0 \Leftrightarrow$ (M,ξ) is algebraically overtwisted
- (M,ξ) fillable $\Rightarrow AT(M,\xi) = \infty$
- $\forall k, \exists (M_k, \xi_k) \text{ with } \mathsf{AT}(M_k, \xi_k) = k.$

Corollary: $(M_k, \xi_k) \xrightarrow{\text{contact surgery}} (M_\ell, \xi_\ell) \Rightarrow \ell \ge k.$



Symplectic Field Theory

(Eliashberg-Givental-Hofer '00 + Cieliebak-Latschev '09)

 (M,ξ) with Reeb vector field \rightsquigarrow $\mathcal{P} := \{ \text{periodic Reeb orbits on } M \}.$

 $\mathcal{A} :=$ graded commutative algebra with unit and generators $\{q_{\gamma}\}_{\gamma \in \mathcal{P}}$.

 $\mathcal{W} := \{ \text{formal power series } F(q_{\gamma}, p_{\gamma}, \hbar) \} \text{ with,} \\ [p_{\gamma}, q_{\gamma'}] = \delta_{\gamma, \gamma'} \hbar. \\ F \in \mathcal{W}, \text{ substitute } p_{\gamma} := \hbar \frac{\partial}{\partial q_{\gamma}} \rightsquigarrow \text{ operator} \\ D_F : \mathcal{A}[[\hbar]] \to \mathcal{A}[[\hbar]] \\ \text{"Theorem": There exists } \mathcal{H} \in \mathcal{W} \text{ with} \\ \mathcal{H}^2 = 0 \text{ such that } D_{\mathcal{H}}(1) = 0 \text{ and} \\ H_*^{\mathsf{SFT}}(M, \xi) := H_*(\mathcal{A}[[\hbar]], D_{\mathcal{H}}) := \frac{\ker D_{\mathcal{H}}}{\operatorname{im } D_{\mathcal{H}}}$

is a contact invariant.

Symplectic cobordism $(M_-, \xi_-) \prec (M_+, \xi_+)$ \rightsquigarrow natural map

$$H_*^{\mathsf{SFT}}(M_+,\xi_+) \to H_*^{\mathsf{SFT}}(M_-,\xi_-)$$

preserving elements of $\mathbb{R}[[\hbar]]$.

Example

If no periodic orbits, then $H_*^{\mathsf{SFT}}(M,\xi) = \mathbb{R}[[\hbar]].$

Definition (Latschev-W.). We say (M,ξ) has **algebraic** *k*-torsion if $[\hbar^k] = 0 \in H^{SFT}_*(M,\xi).$

 $\mathsf{AT}(M,\xi) := \sup\left\{k \mid [\hbar^{k-1}] \neq 0 \in H^{\mathsf{SFT}}_*(M,\xi)\right\}$

Example

Overtwisted \Rightarrow

all "interesting" contact invariants vanish:

 $H_*^{\mathsf{SFT}}(M,\xi) = \{0\} \Rightarrow [1] = 0 \Rightarrow \mathsf{AT}(M,\xi) = 0.$

Theorem. Algebraic k-torsion \Rightarrow not fillable.



A beautiful idea (Witten '82 + Floer '88):

(X,g) Riemannian manifold, $f : X \to \mathbb{R}$ generic Morse function. Then singular homology

$$H_*(X;\mathbb{Z}) \cong H_*\left(\mathbb{Z}^{\#\operatorname{Crit}(f)}, d_f\right),$$

where d_f counts rigid gradient flow lines,

$$\dot{x}(t) + \nabla f(x(t)) = 0.$$



SFT of $(M, \xi = \ker \alpha)$: " ∞ -dimensional Morse theory" for the contact action functional

$$\Phi: C^{\infty}(S^1, M) \to R: x \mapsto \int_{S^1} x^* \alpha,$$

with $Crit(\Phi) = \{periodic \text{ Reeb orbits}\}.$

Gradient flow:

Consider 1-parameter families of loops $\{u_s \in C^{\infty}(S^1, M)\}_{s \in \mathbb{R}}$ with

 $\partial_s u_s + \nabla \Phi(u_s) = 0.$

 \rightsquigarrow cylinders $u : \mathbb{R} \times S^1 \to \mathbb{R} \times M$ satisfying the nonlinear Cauchy-Riemann equation

$$\partial_s u + J(u) \,\partial_t u = 0$$

for an almost complex structure J on $\mathbb{R} \times M$.

For a symplectic cobordism W and Riemann surface Σ , consider *J*-holomorphic curves

$$u: \Sigma \setminus \{z_1, \ldots, z_n\} \to W$$

approaching Reeb orbits at the punctures.



The Cauchy-Riemann equation is **elliptic**: $\|u\|_{W^{1,p}} \leq \|u\|_{L^{p}} + \|\partial_{s}u + i \partial_{t}u\|_{L^{p}}$ $\Rightarrow \text{ Spaces of holomorphic curves are (often)}$

- smooth finite-dimensional manifolds,
- compact up to *bubbling / breaking*.



Definition of ${\mathcal H}$

 $\Gamma^\pm := (\gamma_1^\pm, \dots, \gamma_{k_\pm}^\pm)$ lists of Reeb orbits

 $\mathcal{M}_g(\Gamma^+, \Gamma^-) := \{ \text{ rigid } J\text{-holomorphic curves}$ in $\mathbb{R} \times M$ with genus g, ends at $\Gamma^{\pm} \} / parametrization$

$$\mathcal{H} := \sum_{g, \Gamma^+, \Gamma^-} \# \left(\mathcal{M}_g(\Gamma^+, \Gamma^-) / \mathbb{R} \right) \hbar^{g-1} q^{\Gamma^-} p^{\Gamma^+}$$



SFT compactness theorem: $\overline{\mathcal{M}}_{g}(\Gamma^{+}, \Gamma^{-}) = \{J\text{-holomorphic buildings}\}$

 \mathcal{H}^2 counts the boundary of a 1-dimensional space $\Rightarrow \mathcal{H}^2 = 0$.

Example

Suppose $\mathbb{R} \times M$ has exactly one rigid *J*-holomorphic curve, with genus 0, no negative ends, and positive ends at orbits $\gamma_1, \ldots, \gamma_k$.



Then

$$\mathcal{H} = \hbar^{-1} p_{\gamma_1} \dots p_{\gamma_k}.$$

Substituting $p_{\gamma_i} = \hbar \frac{\partial}{\partial q_{\gamma_i}}$ gives

$$D_{\mathcal{H}}(q_{\gamma_1} \dots q_{\gamma_k}) = \hbar^{k-1}$$
$$\Rightarrow [\hbar^{k-1}] = 0 \in H_*^{\mathsf{SFT}}(M, \xi)$$

 $\Rightarrow \mathsf{AT}(M,\xi) \leq k-1.$

Why $(M_2, \xi_2) \prec (M_1, \xi_1)$ is not true:



Some open questions and partial answers

- 1. What geometric conditions correspond to $AT(M,\xi) = k?$
 - Overtwistedness, Giroux torsion, planar torsion:
 C. Wendl, A hierarchy of local filling obstructions for contact 3-manifolds, Preprint 2010, arXiv:1009.2746.

2. Interesting examples beyond dimension 3?

- Higher-dimensional overtwisted disks:
 K. Niederkrüger, *The plastikstufe—a generalization of the overtwisted disk to higher dimensions*, Algebr. Geom. Topol. 6 (2006), 2473-2508.
 F. Bourgeois, K. Niederkrüger, *PS-overtwisted contact manifolds are algebraically overtwisted*, in preparation.
- Higher-dimensional Giroux torsion:

P. Massot, K. Niederkrüger and C. Wendl, *Weak and strong fillability of higher dimensional contact mani-folds*, to appear in Invent. Math., Preprint 2011, arXiv:1111.6008.

- 3. Can contact structures with $AT(M,\xi) \ge k$ be classified???
 - Overtwisted contact structures are flexible: Y. Eliashberg, *Classification of overtwisted contact structures on 3-manifolds*, Invent. Math. **98** (1989), 623-637.
 - Coarse classification—finitely many have AT(M, ξ) ≥ 2:
 V. Colin, E. Giroux and K. Honda, *Finitude homotopique et isotopique des structures de contact tendues*, Publ. Math. Inst. Hautes Études Sci. **109** (2009), no. 1, 245-293.

Main reference

 Janko Latschev and Chris Wendl, Algebraic torsion in contact manifolds, Geom. Funct. Anal. 21 (2011), no. 5, 1144-1195, with an appendix by Michael Hutchings.

Acknowledgment

Contact structure illustrations by Patrick Massot: http://www.math.u-psud.fr/~pmassot/



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