

# Differential Geometry II

## Almost Complex Manifolds,

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# Complex Vector Bundles

**Lemma 61:** Let  $\nabla$  be a connection on the complex vector bundle  $E \xrightarrow{\pi} M$ . Then the following conditions are equivalent:

(i)  $\nabla J \equiv 0$ ,

(ii) For any smooth  $f : M \rightarrow \mathbb{C}$  and section  $\sigma : M \rightarrow E$  we have

$$\nabla(f\sigma) = \underline{df}\sigma + f\nabla\sigma$$

(iii) The connection 1-form w.r.t. any complex trivialization has the form  $A \in \Omega^1(U; M(k, \mathbb{C}))$  with  $M(k, \mathbb{C}) \subset M(2k; \mathbb{R})$  understood as (real) subalgebra.

Such a connection is called a **complex connection**.

# Complex Vector Bundles

Proof of Lemma 61: (i)  $\Rightarrow$  (iii)

$\nabla \mathcal{J} \equiv 0$ . Choose cplx trivialization

$$\begin{aligned} &= (\pi, \varphi) \\ \underline{\Phi}: \pi^{-1}(U) &\rightarrow U \times \mathbb{C}^k \\ &= U \times \mathbb{R}^{2k} \end{aligned}$$

for  $e \in \pi^{-1}(z)$   $\underline{\Phi}(\mathcal{J}_{\pi(e)} e) = (\pi(e), i \varphi(e))$

$$i \cdot v \hat{=} \begin{pmatrix} i & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} v =: \mathcal{J}_0$$

Let  $A \in \Omega^1(U, \mathcal{M}(2k, \mathbb{R}))$  be the corresponding connection 1-form.

mult. by  $i$   
 $\downarrow$

$$\nabla \mathcal{J} \equiv 0 \Leftrightarrow (d + A) \cdot \mathcal{J}_0 - \mathcal{J}_0 \cdot (d + A) = 0$$

$$(\nabla \mathcal{J})^\sigma = \mathcal{P}(\mathcal{J}^\sigma) - \mathcal{J} \cdot \mathcal{P}^\sigma \Leftrightarrow A \cdot \mathcal{J}_0 - \mathcal{J}_0 \cdot A = 0$$

def. of  $\mathbb{C}$ -mult  $\Leftrightarrow A$  is  $\mathbb{C}$ -linear

$$\Rightarrow \underline{A \text{ is } \mathbb{C}\text{-linear, i.e. } A \in \mathcal{M}(k, \mathbb{C})} \quad \underline{A(a+ib)v} = \underline{A(av + b\mathcal{J}_0(v))} = \underline{aAv + b\mathcal{J}_0 Av} = \underline{(a+ib)Av}$$

# Hermitian Vector Bundles

**Definition 62:** (i) Let  $E \xrightarrow{\pi} M$  be a complex vector bundle. A Hermitian structure on  $E$  is a smooth family  $\{h_p\}_{p \in M}$  of Hermitian products on  $E_p$ , i.e.  $\mathbb{R}$ -bilinear forms which are  $\mathbb{C}$ -linear in the first and  $\mathbb{C}$ -antilinear in the second component, satisfy  $h_p(w, v) = \overline{h_p(v, w)}$  for  $v, w \in E_p$  and  $h_p(v, v) > 0$  if  $v \neq 0$ .

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*Remark:*  $h$  is determined by  $g$  and, obviously, vice versa. We have

$$h(\cdot, \cdot) := g(\cdot, \cdot) + ig(\cdot, J\cdot) \quad (\in \mathbb{C})$$

(Exercise)

# Hermitian Vector Bundles

**Lemma 63:** (i) Let  $(E, h)$  be a Hermitian vector bundle over a manifold  $M$ . Then the local trivializations  $\Phi : \pi^{-1}(U) \rightarrow U \times \mathbb{C}^k$  can be chosen to be Hermitian isomorphisms.



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(iii) W.r.t. a trivialization described in (i) the connection 1-form and the curvature satisfy

$$A_k^\ell = -\overline{A_\ell^k} \quad \text{and} \quad F_k^\ell = -\overline{F_\ell^k}.$$

*Proof:* Exercise  $\square$

Remark:  $A \in \Omega^1(U, \underline{u}(k))$ ,  $F \in \Omega^2(U, \underline{u}(k))$   
 $\underline{u}(k) = \{ B \in M(k; \mathbb{C}) \mid B = -\overline{B}^T \}$ .

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*Remark:* (a) As seen above,  $(g, J)$  determine via  $h := g - i\omega$  a Hermitian structure on  $TM$ .

(b)  $\omega$  is non-degenerate: at any  $p \in M$ : the linear map

$$X \in T_p M \mapsto \omega(X, \cdot) \in T_p^* M$$

is an isomorphism.

*Examples:* (1)  $M = \mathbb{C}^n$ . Then  $T_p \mathbb{C}^n \cong \mathbb{C}^n$  and for  $X \in T_p \mathbb{C}^n$

$$J_p(X) := iX$$

and the standard Hermitian form  $\langle \cdot, \cdot \rangle$ .

# Almost Complex Structures

Examples: (2) Let  $(\Sigma, g)$  be an oriented surface with a Riemannian metric  $g$ . For  $X \in T_p \Sigma$  we define  $J_p(X)$  by requiring, that  $\{X; J_p(X)\}$  is an oriented orthonormal basis of  $(T_p \Sigma, g_p)$ .  $J_p(X)$  is the counterclockwise rotated  $X$ !  $g$  defines a Hermitian structure on  $(\Sigma, J)$ .

$$\|X\|_g = 1$$





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$J$  is unchanged if we replace  $g$  by  $\lambda^2 g$  for  $\lambda : \Sigma \rightarrow \mathbb{R}_+$  smooth.

$$\left\{ X, J_p(X) \right\} \rightsquigarrow \left\{ \frac{X}{\lambda}, \frac{J_p(X)}{\lambda} \right\} \quad J_p^\lambda \left( \frac{X}{\lambda} \right) = \frac{J_p(X)}{\lambda}$$

$$\frac{1}{\lambda} J_p^{\lambda^2}(X) \Rightarrow J_p^\lambda(X) = J_p(X)$$

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There exists an atlas of  $\Sigma$  such that for each chart  $(U, \varphi, V)$

$$d\varphi \circ i = J \circ d\varphi.$$

$$\varphi : V \subset \mathbb{R}^2 \rightarrow U \subset \Sigma$$

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*$g, \lambda^2 g \dots$  conformally equivalent.*

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$(\Sigma, J)$  is called **Riemann surface**,  $J$  its **conformal structure**. In Algebraic Geometry,  $(\Sigma, J)$  is called **complex curve** if  $\partial \Sigma = \emptyset$ .

# Kähler Manifolds

**Definition 65:** Let  $(M, J)$  be an almost complex manifold. The **Nijenhuis-Tensor**,  $N_J$  is the  $(1, 2)$ -tensor given on (local) vector fields  $X, Y$  by

$$N_J(X, Y) := [X, Y] + J[JX, Y] + J[X, JY] - [JX, JY].$$

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$\nabla$  is a complex connection of  $(TM, J)$  if and only if  $d\omega = 0$  and the Nijenhuis-tensor  $N_J \equiv 0$



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*Proof:* ( $\Rightarrow$ ) Assume  $\nabla$  is complex, i.e.  $\nabla J = 0$ . Moreover, since  $\nabla$  is metric we have  $\nabla g = 0$ .

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$$\nabla\omega = -\underbrace{\nabla g}_{=0}(\cdot, J\cdot) - g(\cdot, \underbrace{\nabla J}_{=0}\cdot)$$

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Cartan's formula (see Problem Set 6) for  $d\omega$  reads  $X, Y, Z$  vector fields on  $M$

$$\begin{aligned}d\omega(X, Y, Z) &= X(\omega(Y, Z)) + Y(\omega(Z, X)) + Z(\omega(X, Y)) \\ &\quad - \omega(X, [Y, Z]) - \omega(Y, [Z, X]) - \omega(Z, [X, Y])\end{aligned}$$

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Since  $\nabla$  is torsion free we obtain

$$\begin{aligned}d\omega(X, Y, Z) &= X(\omega(Y, Z)) + Y(\omega(Z, X)) + Z(\omega(X, Y)) \\ &\quad - \omega(X, \underbrace{\nabla_Y Z - \nabla_Z Y}_{= [\cdot, \cdot]}) - \omega(Y, \nabla_Z X - \nabla_X Z) - \omega(Z, \nabla_X Y - \nabla_Y X)\end{aligned}$$

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Finally, last expression yields

$$= \underbrace{X(\omega(Y, Z))} - \omega(\nabla_X Y, Z) - \omega(Y, \nabla_X Z) \\ (\nabla_X \omega)(Y, Z) + (\nabla_Y \omega)(Z, X) + (\nabla_Z \omega)(X, Y) = 0$$

and vanishes since  $\nabla\omega \equiv 0$ .  $\Rightarrow d\omega = 0$

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$$\begin{aligned} N_J(X, Y) &= \underbrace{[X, Y]}_{\text{red}} + \underbrace{J[JX, Y]}_{\text{blue}} + \underbrace{J[X, JY]}_{\text{green}} - \underbrace{[JX, JY]}_{\text{magenta}} \\ &= \underbrace{\nabla_X Y - \nabla_Y X}_{\text{red}} + \underbrace{J(\nabla_{JX} Y - \nabla_Y(JX))}_{\text{blue}} \\ &\quad + \underbrace{J(\nabla_X(JY) - \nabla_{JY} X)}_{\text{green}} - \underbrace{\nabla_{JX}(JY) + \nabla_{JY}(JX)}_{\text{magenta}} \\ &= J((\nabla_X J)Y - (\nabla_Y J)X) - J((\nabla_{JX} J)Y - (\nabla_{JY} J)X) \\ &= 0 \end{aligned}$$



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Need to show that  $\nabla J \equiv 0$  for  $\nabla$  torsion free implies  $N_J \equiv 0$ .

$$N_J(X, Y) = [X, Y] + J[JX, Y] + J[X, JY] - [JX, JY]$$

$$\begin{aligned} &= \nabla_X Y - \nabla_Y X + J(\nabla_{JX} Y - \nabla_Y(JX)) \\ &\quad + J(\nabla_X(JY) - \nabla_{JY} X) - \nabla_{JX}(JY) + \nabla_{JY}(JX) \\ &= J((\nabla_X J)Y - (\nabla_Y J)X) - J((\nabla_{JX} J)Y - (\nabla_{JY} J)X) \\ &= 0 \end{aligned}$$

since  $\nabla J \equiv 0$  and  $(\nabla J)X = \nabla(JX) - J\nabla X$ .

# Kähler Manifolds

( $\Leftarrow$ ) Using Koszul's formula for the Levi-Civita connection  $\nabla$

*X, Y, Z vector fields*

$$2g(\nabla_X Y, Z)$$

$$= X(g(Y, Z)) + Y(g(Z, X)) - Z(g(X, Y))$$

$$+ g([X, Y], Z) - g([Y, Z], X) + g([Z, X], Y)$$

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one obtains a formula like

$$2g((\nabla_X J)Y, Z) = (d\omega)(X, Y, Z) \pm g(X, N_J(Y, Z)), \quad \leftarrow$$

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