# Differential Geometry II <br> Darboux Theorem and Moser Trick 

Klaus Mohnke

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## Isotropic, Coisotropic and Lagrangian Immersions

For a symplectic vector space $(V, \omega)$ and a subspace $U \subset V$ we define

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\operatorname{Ann}_{\omega}(U):=\{v \in V \mid \omega(v, u)=0 \quad \forall u \in U\} .
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$$
\begin{aligned}
& \text { tor all } p \in \mathbb{N} \iota_{*}\left(I_{p} N V\right) A n n_{\omega_{l(p)}}\left(\iota_{*}\left(I_{p} N\right)\right) \\
& \text { i.e. } v \in T_{c(p)} M \quad\left(T_{p} N\right) \\
& \Rightarrow V \in 2_{*}\left(T_{p} N\right) .
\end{aligned}
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Lagrangian if isotropic and coisotropic.
Notice: If $\iota$ is isotropic, then $\operatorname{dim} N \leq \frac{1}{2} \operatorname{dim} M$, coisotropic, then $\operatorname{dim} N \geq \frac{1}{2} \operatorname{dim} M$. Hence, if $\iota$ is Lagrangian, then $\operatorname{dim} N=\frac{1}{2} \operatorname{dim} M$.

Isotropic, Coisotropic and Lagrangian Immersions
Examples: (1) If $\operatorname{dim} N=0$ or $\underline{1}$, then $\iota$ is isotropic. If $\operatorname{dim} N=2 n-1$ or $2 n, \iota$ is coisotropic. $\quad \omega(v, \varphi)=0 \quad \forall V$ $\operatorname{dim} M=2 h$

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(3) The zero section and every fibre in $T^{*} M$ are Lagrangian submanifolds. If $\alpha \in \Omega^{1}(Q)$ then its graph
$\rightarrow \Gamma_{\alpha}:=\left\{\alpha(q) \in T_{q}^{*} Q \mid q \in Q\right\} \subset T^{*} Q$ is Lagrangian if and only if $d \alpha=0$.

$$
\begin{aligned}
& \left.\omega=d \theta=\sum d p_{i} d q_{i} \quad i_{1} \text { associated coand. ( } p_{1} \ldots, p_{4}, q_{1} \ldots, g_{1}\right) \\
& \theta=\left.\sum p_{i} d_{q i} \quad \theta\right|_{\text {zug section }} \equiv 0
\end{aligned}
$$

$$
\begin{aligned}
& \alpha: Q \rightarrow T^{x} Q \quad \alpha^{x} \theta=\alpha \Rightarrow \alpha^{x}(d \theta)=d \alpha
\end{aligned}
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$\Gamma_{\alpha}:=\left\{\alpha(q) \in T_{q}^{*} Q \mid q \in Q\right\} \subset T^{*} Q$ is Lagrangian if and only if $d \alpha=0$.
(4) Let $\varphi:\left(M_{1}, \omega_{1}\right) \rightarrow\left(M_{2}, \omega_{2}\right)$ be a symplectomorphism $\left(\operatorname{dim} M_{1}=\operatorname{dim} M_{2}\right)$. Then the graph

$$
\Gamma_{\varphi}:=\left\{(x, \varphi(x)) \mid x \in M_{1}\right\} \subset M_{1} \times M_{2}
$$

is a Lagrangian submanifold where the symplectic structure on $M_{1} \times M_{2}$ is given by

$$
\omega:=\pi_{1}^{*} \omega_{1}-\pi_{2}^{*} \omega_{1} . \quad\left({ }^{*} \varepsilon \omega_{1} \oplus\left(-\omega_{2}\right)^{\prime \prime}\right)
$$

$$
\text { At (4) } \begin{aligned}
& \Phi: \mu_{1} \rightarrow \Gamma_{y} \quad \Phi(x)=(x, \varphi(x)) \\
& \Phi^{*} \omega=(i d \times \rho)^{*}\left(i_{1}^{x} \omega_{1}-i_{2}^{*} \omega_{2}\right) \\
&=\omega_{1}-\varphi^{*} \omega_{2}=0
\end{aligned}
$$

## Darboux' Theorem

Theorem 99: Let $(M, \omega)$ be a symplectic manifold, $\operatorname{dim} M=2 n$, $p \in M$. There exists a neighborhood $U$ of $p, R>0$ and a symplectomorphisms

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\varphi:(U, \omega) \rightarrow\left(B^{2 n}(R), \omega_{s t}\right)
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i.e. $\varphi$ is a diffeomorphism such that $\varphi^{*} \omega_{s t}=\omega$.

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(2) The quantity

$$
w(M, \omega):=\sup \left\{R>0 \mid \exists \psi: B^{2 n}(R) \hookrightarrow M, \psi^{*} \omega=\omega_{s t}\right\}
$$

is a symplectic invariant, called Gromov width. E.g.

$$
w\left(B^{2}(R) \times \mathbb{R}^{2 n-2}\right)=R .
$$

## Moser's Trick

Lemma 100: Let $(M, \omega)$ be a symplectic manifold.
(1) For a smooth family $\left(\omega_{\tau}\right)_{\tau \in[0,1]}$ of symplectic structures with $\omega_{0}=\omega$ suppose there is a smooth family $\beta_{\tau} \in \Omega^{1}(M)$ such that

$$
\begin{array}{ll}
d \beta_{\tau}=\frac{d}{d \tau} \omega_{\tau} . & \% \nexists \beta_{\tau} \text { if } \\
& \% \omega_{\tau}=e^{\tau} \omega \\
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\frac{d}{d \tau} \Phi_{\tau}=X_{\tau} \circ \Phi_{\tau} \quad<\text { site im-tial values }
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Then

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\Phi_{\tau}^{*} \omega_{\tau}=\omega . \Rightarrow \Phi_{1}^{*} \omega_{1}=\omega_{0}=\omega
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(ii) Differentiating the left hand side of the equation yields

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& \frac{d}{d \tau}\left(\Phi_{\tau}^{*} \omega_{\tau}\right)=\Phi_{\tau}^{*}\left(\mathcal{L}_{X_{\tau}} \omega_{\tau}+\frac{d \omega_{\tau}}{d \tau}\right) \quad \omega_{\tau} \text { sympectic } \\
&\left.\left.=\Phi_{\tau}^{*}\left(X_{\tau}\right\lrcorner d \omega_{\tau}+d\left(X_{\tau}\right\lrcorner \omega_{\tau}\right)+d \beta_{\tau}\right) \Rightarrow d \omega_{\tau}=\mathbf{0} \\
&=\Phi_{\tau}^{*}\left(d\left(-\beta_{\tau}\right)+d \beta_{\tau}\right)=0 . \\
& \text { Coftun }
\end{aligned}
$$

The claim follows. $\square$
Remark: The job consists in establishing the two conditions. To obtain $\beta_{\tau}$ one uses the idea of Poincaré'e Lemma or assumes that $\left[\omega_{\tau}\right] \in H_{D R}^{2}(M)$ is constant and tools from analysis.

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Read the proof of Darboux' Theorem in this light!!

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"nathatical Mulhods...
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(i) Let $\left(v_{1}, \ldots, v_{2 n}\right) \subset \mathbb{R}^{2 n}$ basis such that
$\omega_{0}\left(v_{2 k-1}, v_{2 k}\right)=-\omega_{0}\left(v_{2 k}, v_{2 k-1}\right)=1$ and $\omega_{0}\left(v_{i}, v_{j}\right)=0$ else.

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$\Rightarrow$ We may assume that $\omega_{0}=\omega_{s t}$.
(ii) Let $\omega_{\tau}:=(1-\tau) \omega+\tau \omega_{s t}$. We have $\omega_{\tau, 0}=\omega_{s t}$ for all $\tau . \Rightarrow$ There exists an open neighbourhood $U^{\prime} \subset U$ of $p$ such that

$$
\left.\omega_{\tau}\right|_{U^{\prime}}
$$

is non-degenerate for all $\tau \in[0,1]$.

## Darboux Charts

(iii) ${ }^{1} U^{\prime \prime} \subset U^{\prime}$ and $\beta \in \Omega^{1}\left(U^{\prime \prime}\right)$ such that $\beta_{0}=0$ and $d \beta=\omega$.

Define

$$
\beta_{\tau}:=(1-\tau) \beta+\tau \theta
$$

where $\theta:=\sum_{k=1}^{n} x^{2 k-1} d x^{2 k}$ is the tautological form. $\beta_{\tau, 0}=0$ for all $\tau$. Then $d \beta_{\tau}=\omega_{\tau}$.

$$
\begin{aligned}
d \beta_{T}( & =(1-T) \alpha \beta+T d \theta \\
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(iv) Let $X_{\tau}$ be the vector field on $U^{\prime \prime}$ such that

$$
X \tau\lrcorner \omega_{\tau}=-\beta_{\tau}
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$X_{\tau}(0)=0$ for all $\tau \in[0,1]$. since $\beta_{\tau_{0}} \simeq 0$.

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$\Rightarrow$ there is a neighbourhood $V \subset U^{\prime \prime}$ of $p$ such that for all $q \in V$ there exists a unique solution $\gamma_{q}:[0, \mathcal{1}] \rightarrow U^{\prime \prime}$ of

$$
\dot{\gamma}_{q}(t)=X_{t}\left(\gamma_{q}(t)\right) \longleftarrow
$$

with $\gamma_{q}(0)=q$. Notice $\gamma_{q} \equiv p$ is a globe solution

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\dot{\gamma}_{q}(t)=X_{t}(\gamma(t))
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(v) Define $\Phi_{\tau}: V \rightarrow U$ via $\Phi_{\tau}(q)=\gamma_{q}(\tau)$. Then

$$
\frac{d}{d \tau} \Phi_{\tau}=X_{\tau} \circ \Phi_{\tau}
$$

## Almost Complex Structures

Definition 101: Let $(M, \omega)$ be a symplectic manifold.
(i) An almost complex structure is compatible to $\omega$ if $g(.,):.=\omega(., J$.$) is a Riemannian structure on M$ : Symmefic \& pos. definite

## Almost Complex Structures

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(i) An almost complex structure is compatible to $\omega$ if $g(.,):.=\omega(., J$.$) is a Riemannian structure on M$.
(ii) $\omega$ is taming $J$ if $\omega(X, J X) \geq c\|X\|_{g}^{2}$ for all $X \in T M$, for a constant $c>0$ and a Riemannian metric $g$ with injectivity radius uniformly bounded away from zero and sectional curvature uniformly bounded from above.


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Remark: (1) On a closed manifold any Riemannian metric satisfies the conditions of (ii). In particular, if $\omega$ and $J$ are compatible then $J$ is tamed by $\omega$.
(2) From $g(.,):.=\omega(., J$.$) follows that g$ is symmetric if and only if $g(J X, J Y)=g(X, Y)$.
$\Rightarrow J$ is orthogonal, $h(X, Y):=g(X, Y)+i \omega(X, Y)$ defines a Hermitian structure with Kähler form $\omega$.

Almost Complex Structures
Proposition 102: Let $M$ be a closed manifold, $J$ an almost complex structure tamed by symplectic forms $\omega_{k}, k=0,1$, such that $\left[\omega_{0}\right]=\left[\omega_{1}\right] \in H_{D R}^{2}(M)$. Then there is a symplectomorphism $\varphi: M \rightarrow M, \varphi^{*} \omega_{1}=\omega_{0}$.
Proof: $\quad \omega_{1}-\omega_{0}=\alpha \beta \quad \beta \in \Omega^{\prime}\left(M_{1}\right)$

$$
\begin{aligned}
& \omega_{T}=(1-T) \omega_{0}+T \omega_{1}=\omega_{0}+T d \beta \\
& \beta_{T}=\beta: \quad d \beta_{T}=d \beta=\frac{d}{d T} \omega_{T}
\end{aligned}
$$

$X_{T}: \quad X_{T}-\omega_{T}=-\beta \quad$ smooth flunky of recto fields on M
$M$ clone $\Rightarrow 7 \Phi_{T}: h \rightarrow M_{1}$ differ.

$$
\Phi_{0}=i d_{m} \quad \frac{d}{d_{1}} \Phi_{T}=X_{T} \cdot \Phi T
$$

Meson's trickle $\Rightarrow \Phi_{1}^{*} w_{1}=w_{0}$

Almost Complex Structures
Theorem 103: (i) Let $(M, \omega)$ be a symplectic manifold. The space of compatible almost complex structures

$$
\mathcal{J}(M, \omega):=\{J \mid J \text { almost complex structure compatible with } \omega\}
$$

is a non-empty contractible space.
(ii) Assume that on a open subset $U$ there is an almost copmplex structure tamed by $\omega$ such that $M \backslash U$ is compact, then there is an almost complex structure on $M$ which is tamed by $\omega$.


$$
=S_{p}\left(T_{p} R, \omega_{p}\right) / u(
$$

$$
\simeq \mathbb{R}^{N(n)}
$$

$$
u\left(T_{p} A_{1}, \omega_{p}, J_{0}\right)
$$

Siege's upi half face.
$\leadsto$ forme hade wo $M \& J(H, \omega)=$ race of Eectias $D$

$$
\begin{aligned}
& S_{p}\left(T_{p} h, w_{p}\right) \\
& =\left\langle\phi: T p h-1 T_{p h} \operatorname{lin} \cdot i 50\right| \\
& \left.d^{*} \omega_{p}=\omega_{p}\right\}
\end{aligned}
$$

## Chern Classes of $\omega$

Remark: The closedness $d \omega=0$ plays no role in the proof of Theorem 103. The existence of an almost complex structure provides an obstruction to the existence of a symplectic structure.

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For example: An oriented closed 4-manifold admits an almost complex structure (inducing this orientation) if and only if there is a integer class $c \in H_{D R}^{2}(M)$ such that

$$
\int_{M} c^{2}=2 \chi(M)+3 \sigma(M)
$$

$S^{4}$ and $2 k \mathbb{C} P^{2} \sharp 2 \ell \overline{\mathbb{C} P^{2}}$ do not admit almost complex structures for any orientation.

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Definition 104: The Chern classes of a symplectic manifold $(M, \omega)$ are the Chern classes $c_{k}(T M, J)$ of an almost complex structure $J$ which is compatible to $\omega$.

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Definition 104: The Chern classes of a symplectic manifold $(M, \omega)$ are the Chern classes $c_{k}(T M, J)$ of an almost complex structure $J$ which is compatible to $\omega$.
Remark: Since the space of such structures is connected via the Chern-Weil construction we see that $c_{k}(M, \omega)$ is well-defined, i.e. does not depend on J.

## Proof of Theorem 103

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