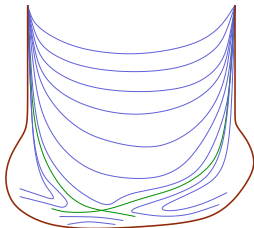


On Symplectic Manifolds with Contact Boundary or “when is a Stein manifold merely symplectic?”

Chris Wendl

Humboldt-Universität zu Berlin

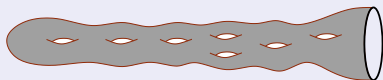
February 9, 2018



What do these questions have in common?

1. Topology

Given a closed manifold M , is it the boundary of a compact manifold?



2. Global analysis

Given two (almost) complex manifolds W and W' , what is the structure of the space of **holomorphic maps** $W \rightarrow W'$?

Is it smooth? Is it compact? Is its topology interesting?

3. Hamiltonian dynamics

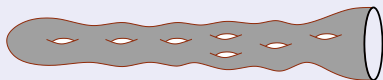
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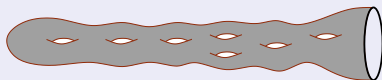
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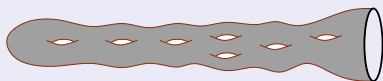
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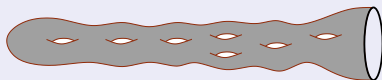
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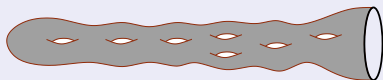
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- **Contact structures** ($\dim M = 2n - 1$)

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Theorem (Rabinowitz-Weinstein '78)

*Every star-shaped hypersurface in \mathbb{R}^{2n} has a **periodic** Hamiltonian orbit.*

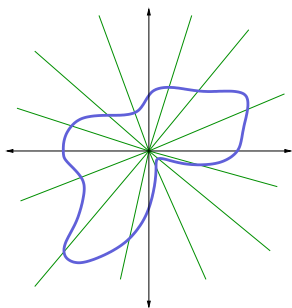
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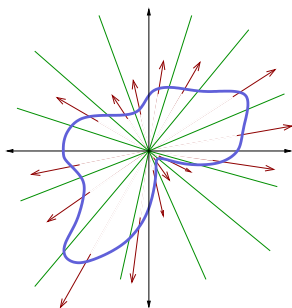
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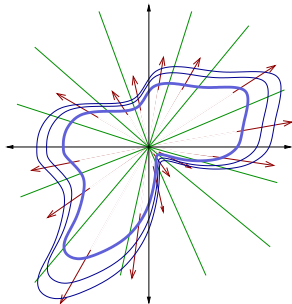
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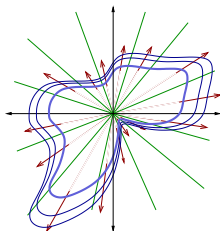
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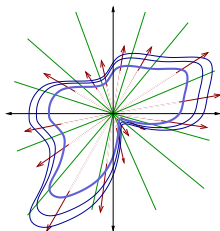
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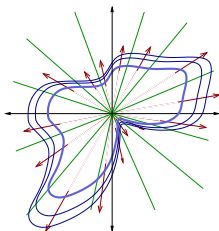
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A **Stein manifold** is a complex manifold (W, J) with a proper holomorphic embedding

$$(W, J) \hookrightarrow (\mathbb{C}^N, i).$$

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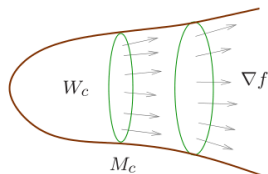
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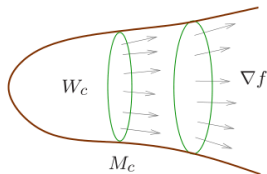


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The maximal complex subbundle

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is then a **contact structure** on M_c , i.e. it is **maximally nonintegrable**.



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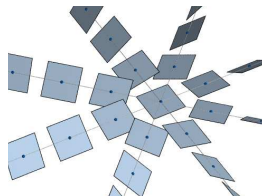
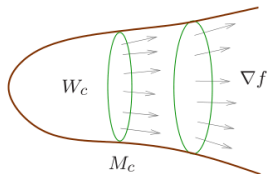
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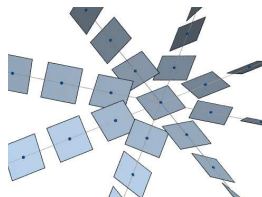
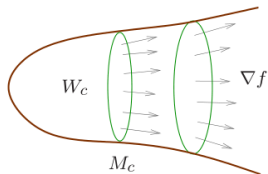
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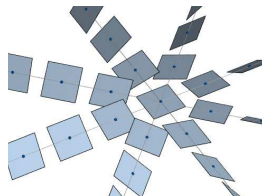
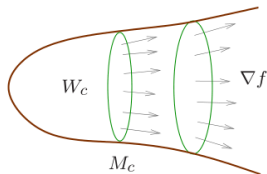
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Do Hamiltonian flows on compact contact hypersurfaces always have periodic orbits?

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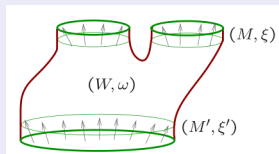
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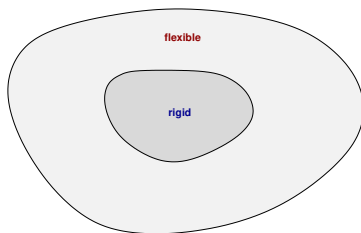
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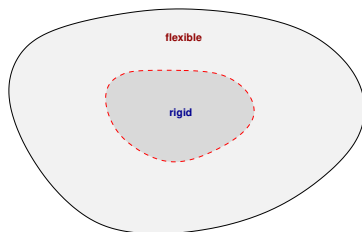
SYMPLECTIC GEOMETRY



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SYMPLECTIC GEOMETRY



Insight: The interesting questions are on the borderline.

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Examples of symplectic flexibility

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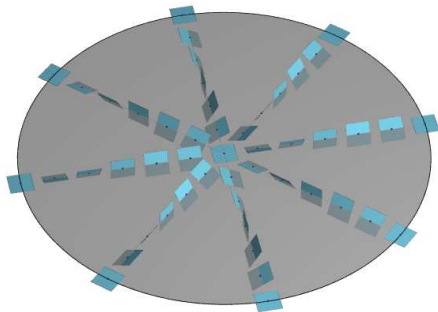
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- Two “overtwisted” contact structures ξ_1, ξ_2 are **isotopic** \Leftrightarrow they are **homotopic**. [Eliashberg 1989] + [Borman-Eliashberg-Murphy 2014]



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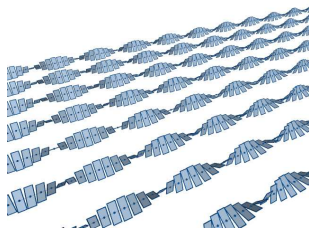
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Rigidity (“hard”) comes from **invariants**: *Gromov-Witten*, *Floer homology*, *symplectic field theory (SFT)*, *Seiberg-Witten*...

Examples of symplectic rigidity

- (S^3, ξ_{std}) has a **unique Stein filling** up to deformation. [Gromov 1985], [Eliashberg 1989]
- \exists **symp. fillable** contact manifolds with **no Stein fillings**. [Ghiggini 2005]
- The 3-torus admits an infinite sequence of contact structures that are **homotopic** but **not isotopic**. [Giroux 1994]
Only the first is **fillable** [Eliashberg 1996], and its filling is **unique**. [W. 2010]



The middle ground: quasiflexibility

Stein is generally **more rigid** than *symplectic*, e.g. Ghiggini '05 proved

$$\text{Stein}(W) \rightarrow \text{Symp}^{\text{convex}}(W)$$

is **not always surjective** on π_0 .

Open question

Is there a manifold with two Stein structures that are symplectomorphic but **not Stein homotopic**?

Main theorem (Lisi, Van Horn-Morris, W. '17)

Suppose $\dim_{\mathbb{R}} W = 4$, J_0 and J_1 are Stein structures on W , and J_0 admits a compatible **Lefschetz fibration of genus 0**. Then

$$J_0 \stackrel{\text{Stein}}{\sim} J_1 \iff \omega_{J_0} \stackrel{\text{symp}}{\sim} \omega_{J_1}.$$

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$\pi : W^4 \rightarrow \Sigma^2$ with isolated critical points

$$\pi(z_1, z_2) = z_1^2 + z_2^2$$

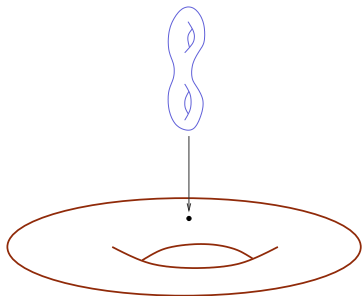
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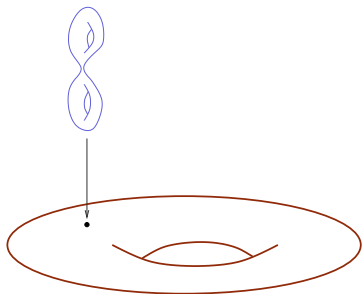


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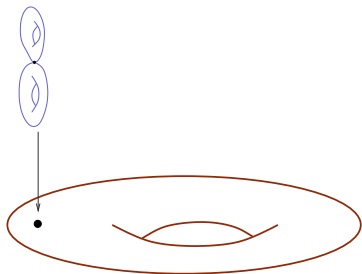


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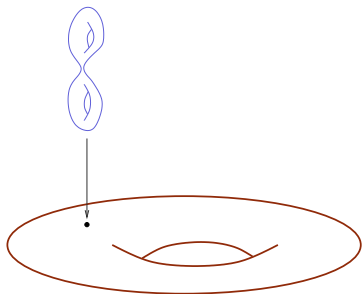


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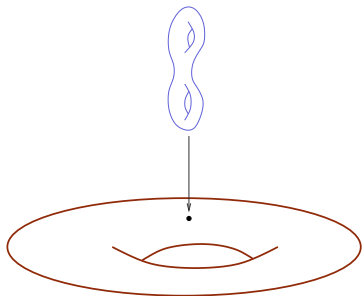


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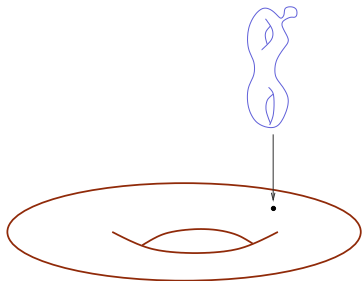


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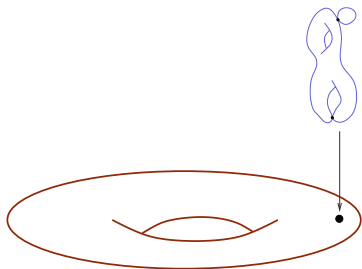


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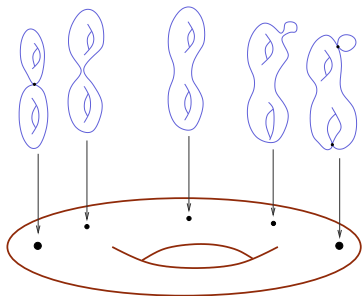


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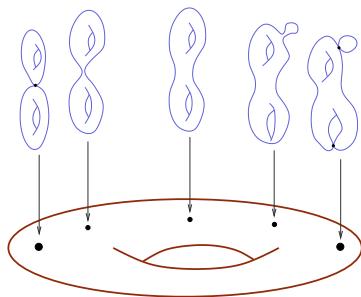


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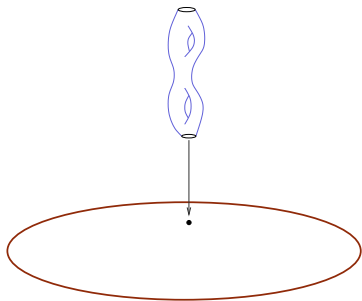
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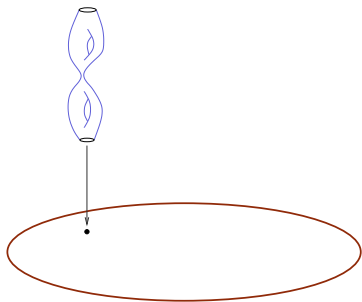
Theorem (Thurston, Gompf)

If $[fiber] \neq 0 \in H_2(W; \mathbb{Q})$, then W admits a canonical deformation class of symplectic forms with $\omega|_{fibers} > 0$.

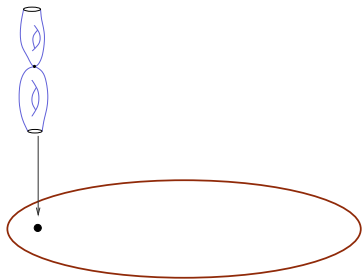
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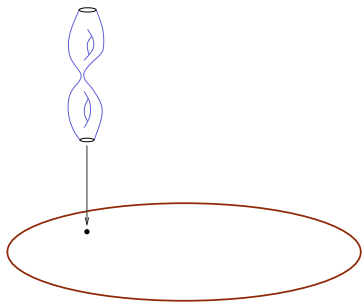
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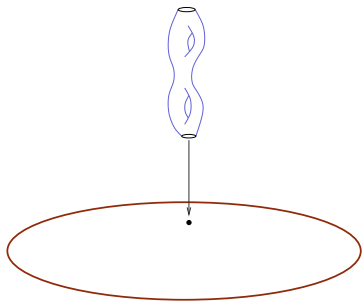
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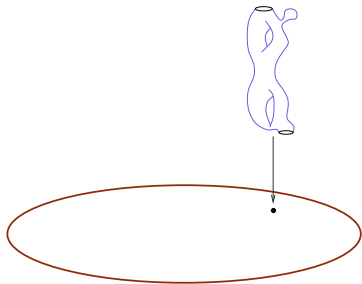
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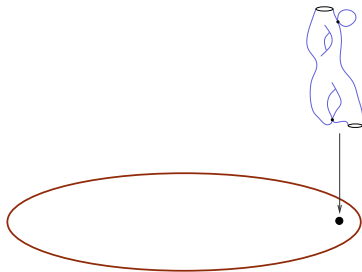
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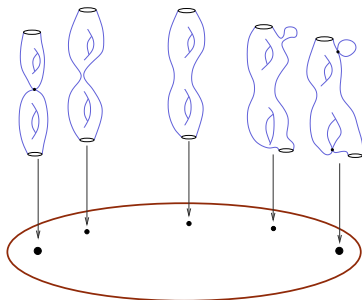
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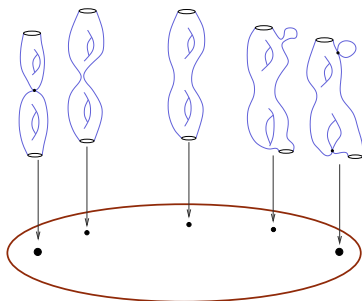
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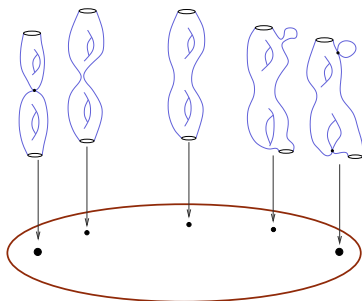


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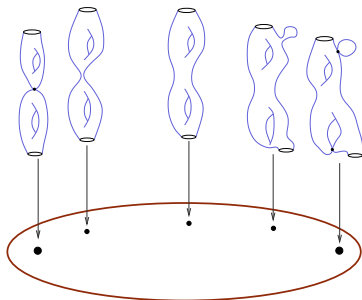
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$\Rightarrow \partial W$ inherits an **open book decomposition**.

Thurston-Gompf for Stein structures



Lemma (Lisi, Van Horn-Morris, W.)

Suppose $\pi : W \rightarrow \mathbb{D}^2$ has **no closed components** in its singular fibers (i.e. π is “allowable”). Then W admits a **canonical deformation class of Stein structures** such that the **fibers are holomorphic curves**, and the contact structure on ∂W is **supported** (in the sense of Giroux) by the induced open book decomposition.

Heavy artillery

Fundamental lemma of symplectic topology (Gromov '85)

On every symplectic manifold (W, ω) , there is a **contractible** space of “tamed” almost complex structures

$$\{J : TW \rightarrow TW \mid J^2 = -\mathbb{1} \text{ and } \omega(X, JX) > 0 \text{ for all } X \neq 0\}.$$

Given a Riemann surface (Σ, j) , a map $u : \Sigma \rightarrow W$ is called **J -holomorphic** if it satisfies the **nonlinear Cauchy-Riemann equation**:

$$Tu \circ j = J \circ Tu$$

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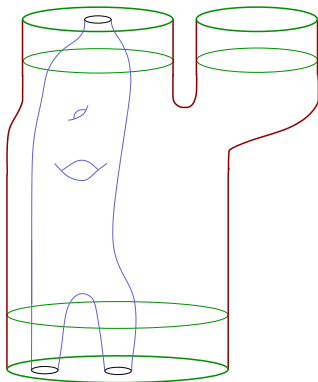
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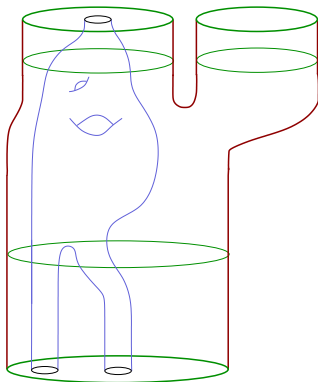


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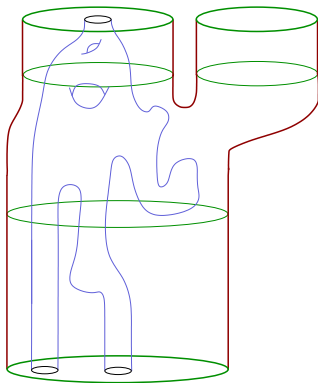


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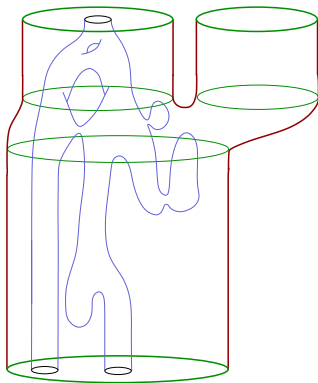


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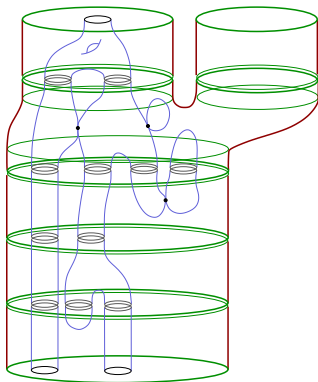


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Switching on the machine...

Lemma (W. '10)

Suppose (W^4, ω_τ) is a 1-parameter family of symplectic fillings of (M^3, ξ) , where ξ is supported by a **planar** open book (i.e. its fibers have genus zero).

Choose a generic family J_τ of ω_τ -tame **almost complex structures** on the symplectic completion $(\widehat{W}, \widehat{\omega}_\tau)$.

Then the open book extends to a smooth family of **Lefschetz fibrations**

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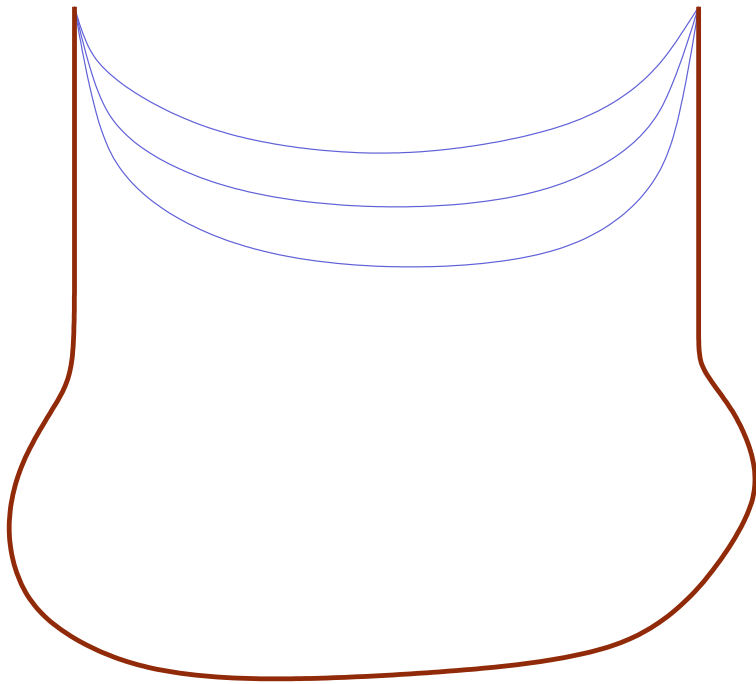
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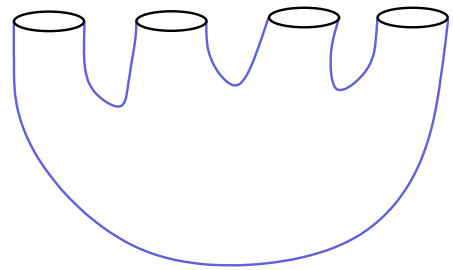
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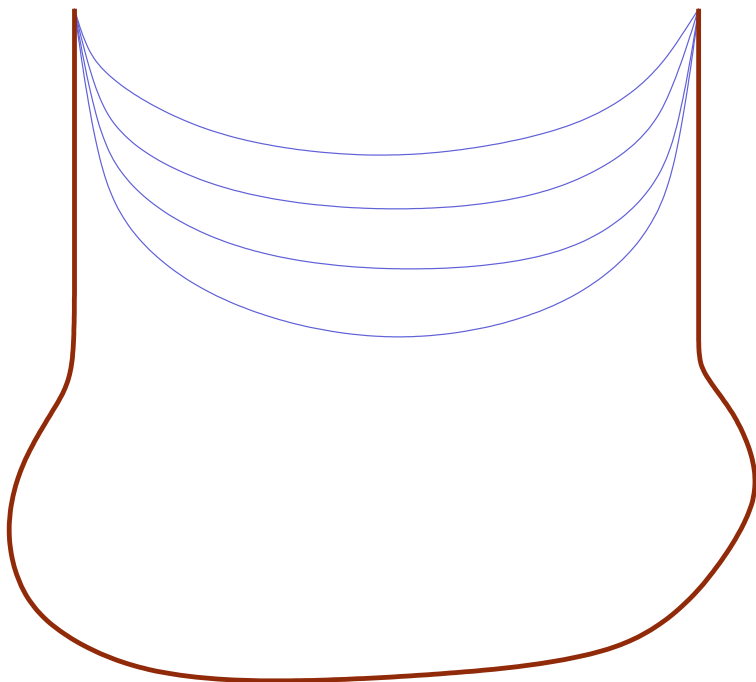
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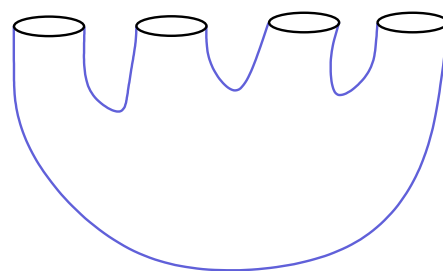


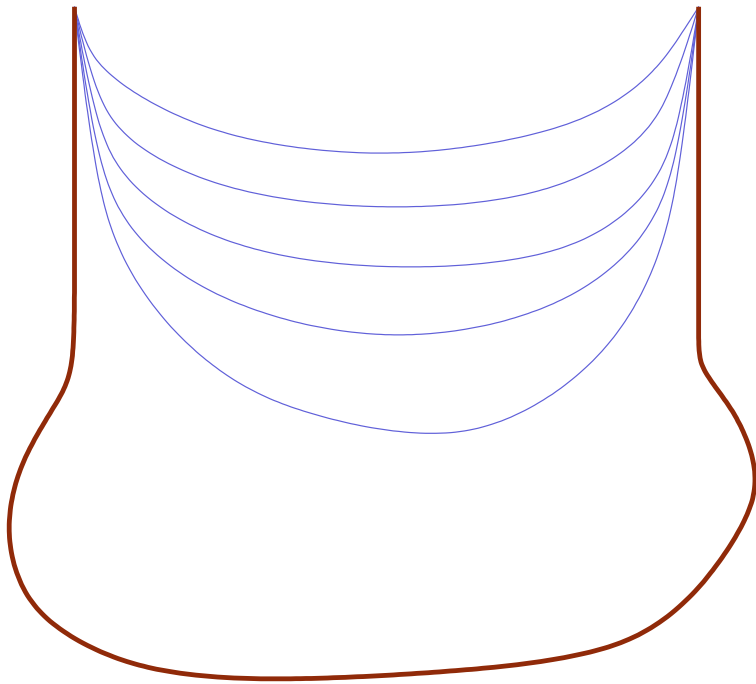
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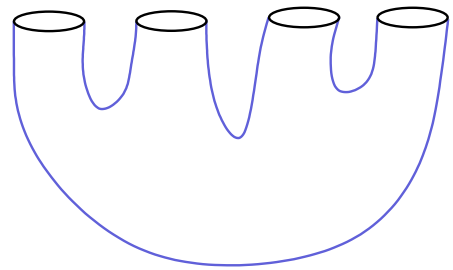


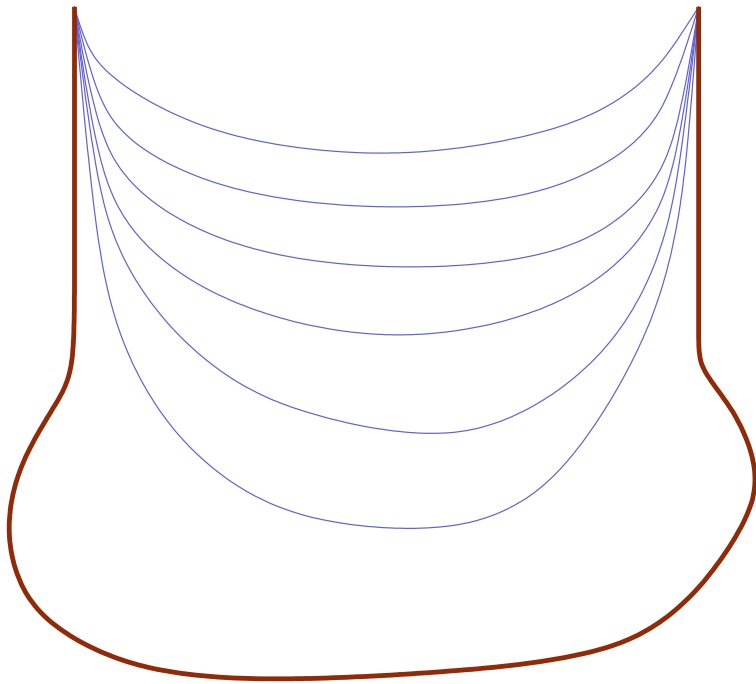
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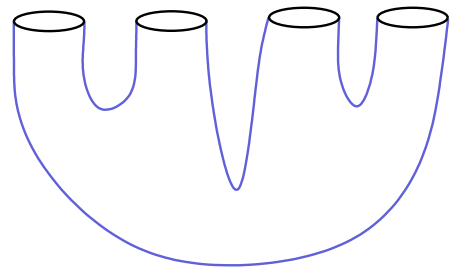


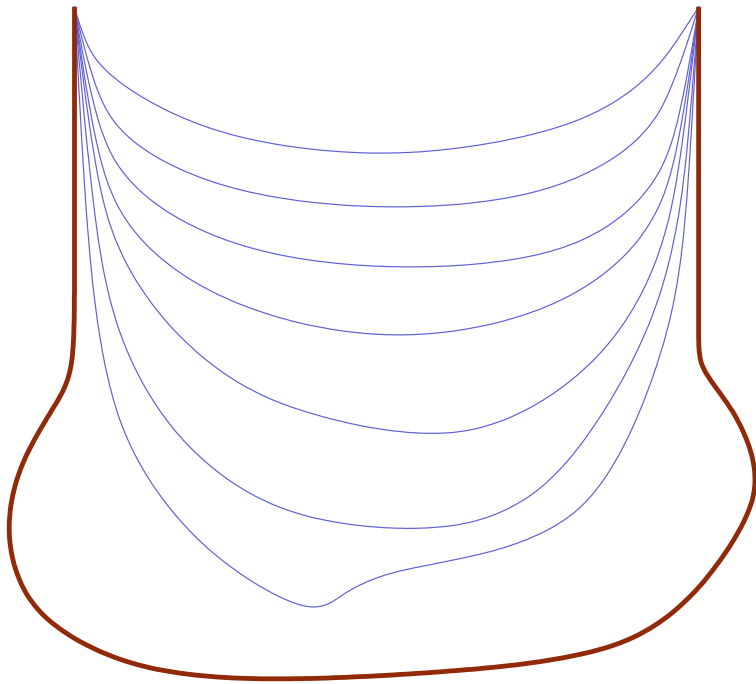
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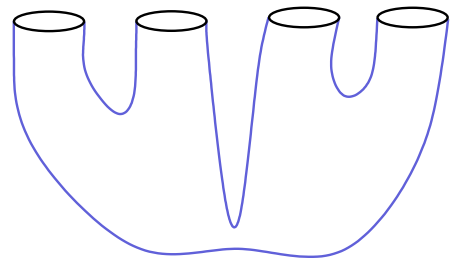


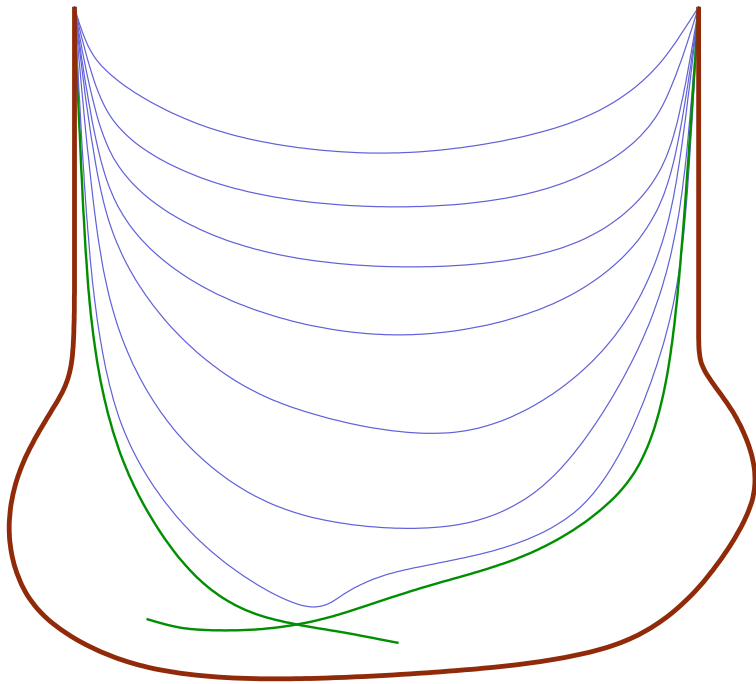
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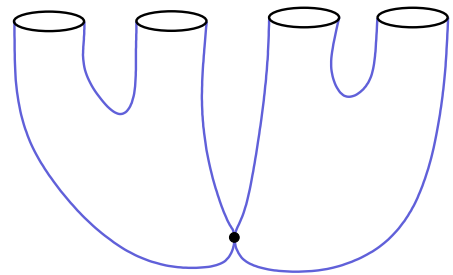


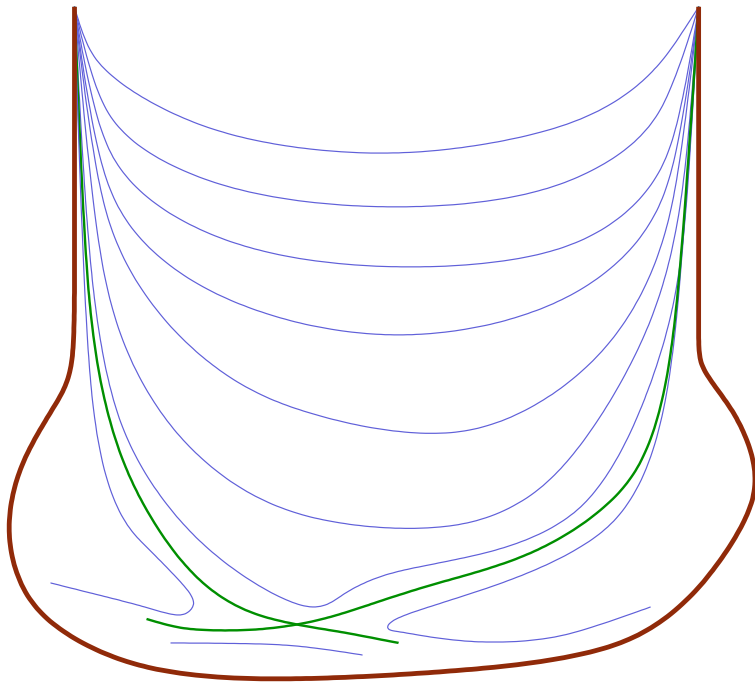
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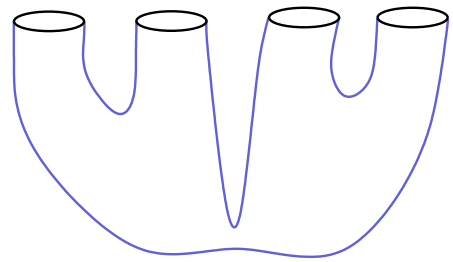


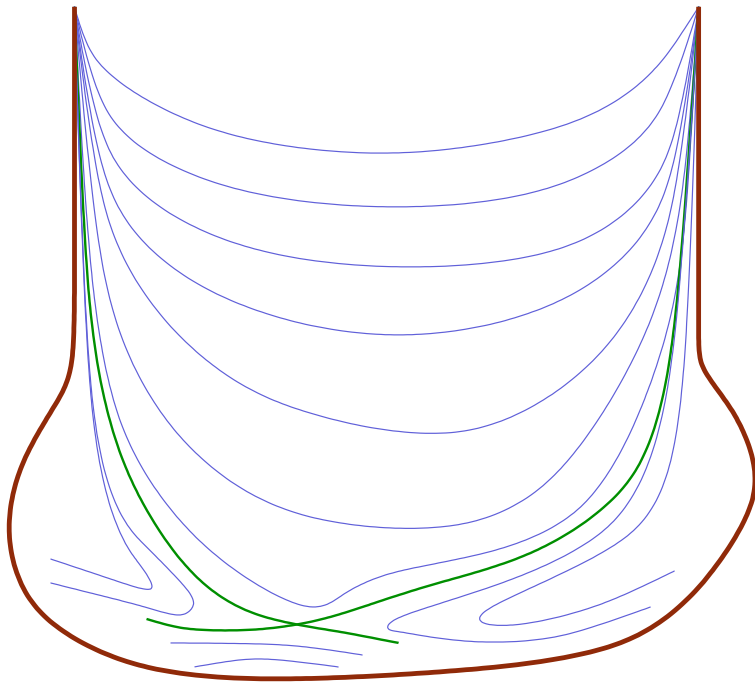
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



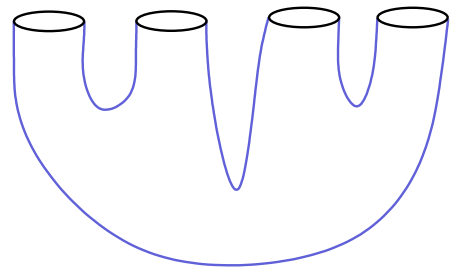


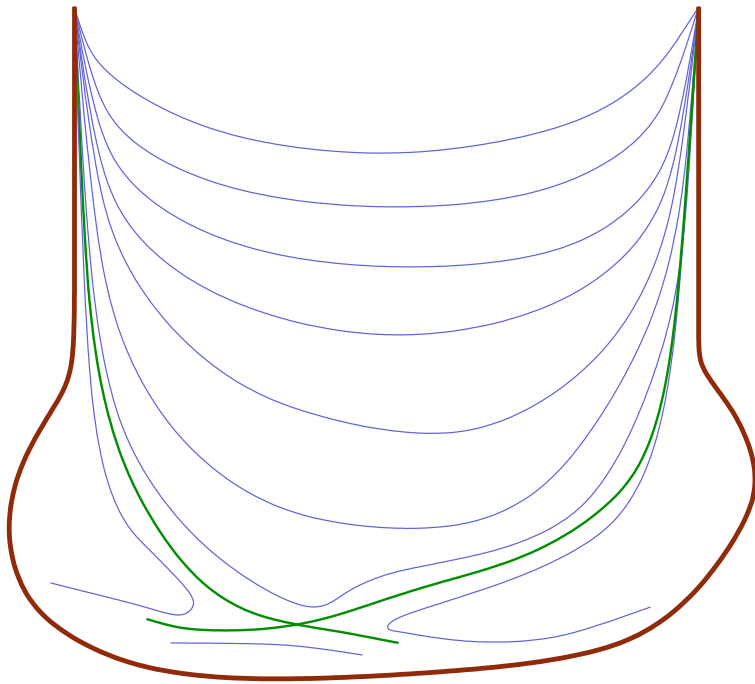
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



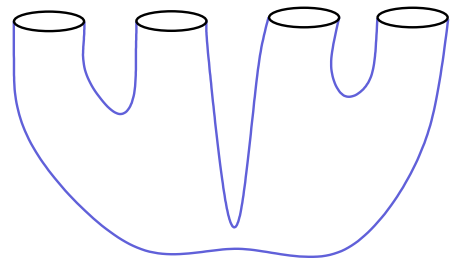


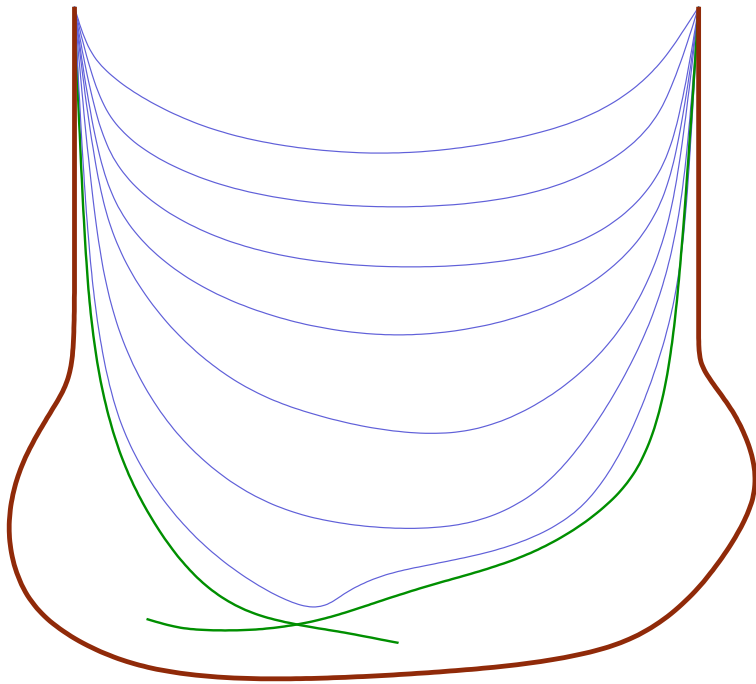
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



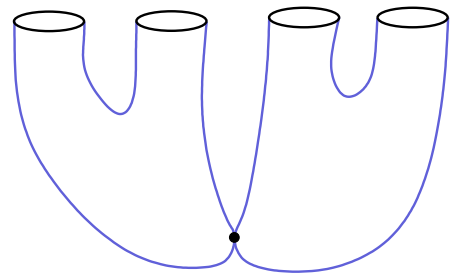


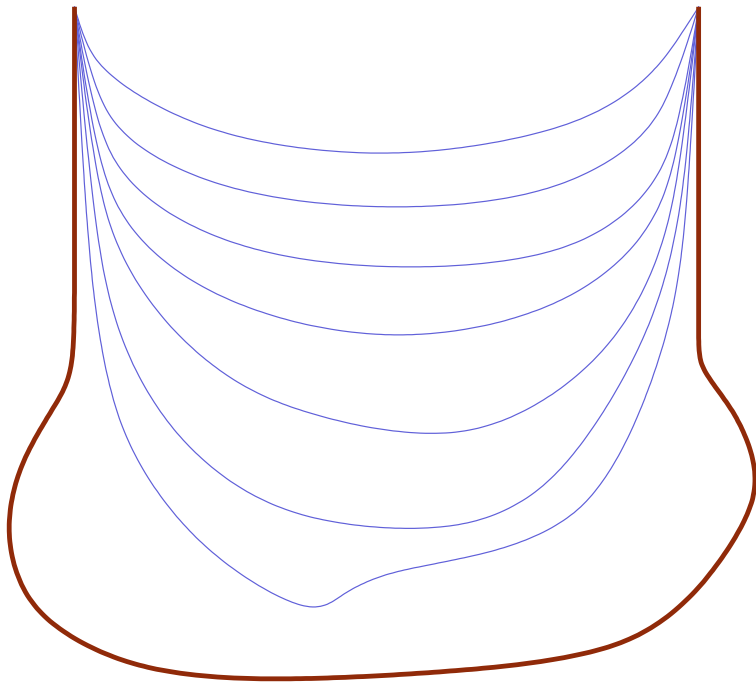
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



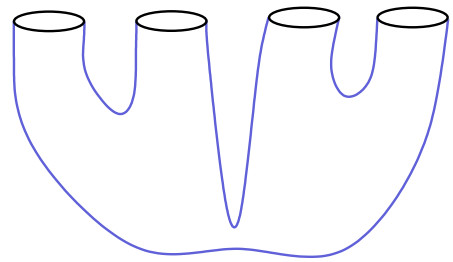


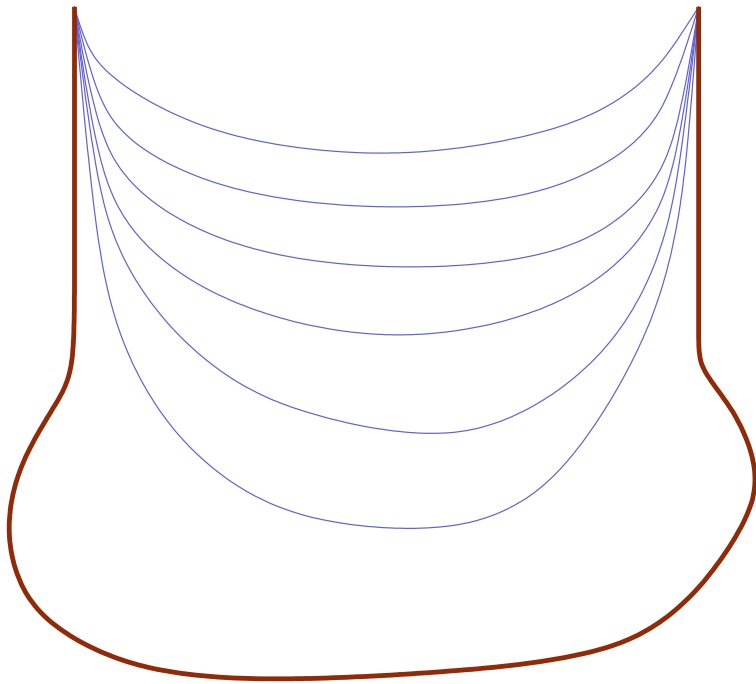
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



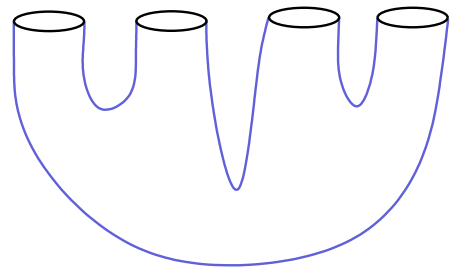


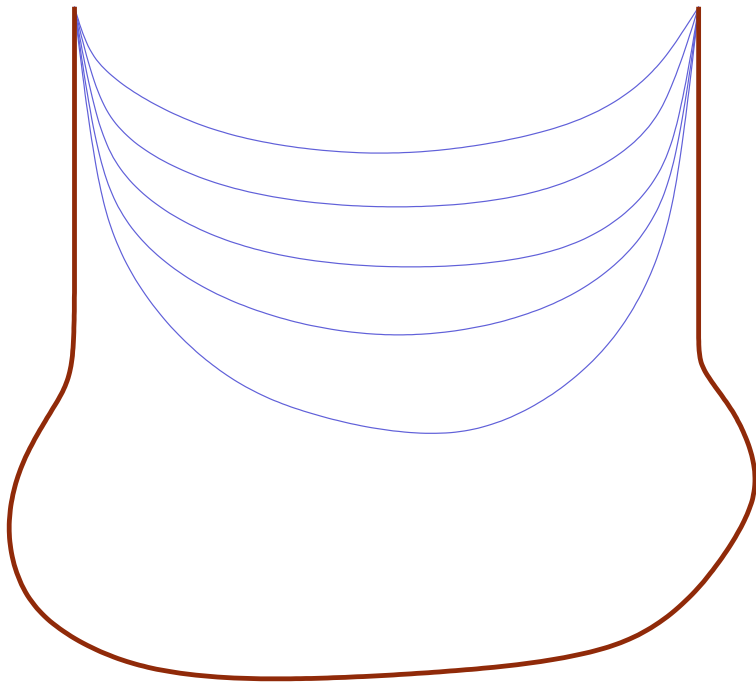
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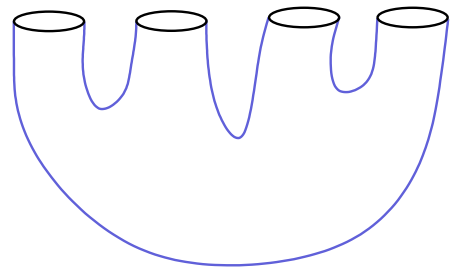


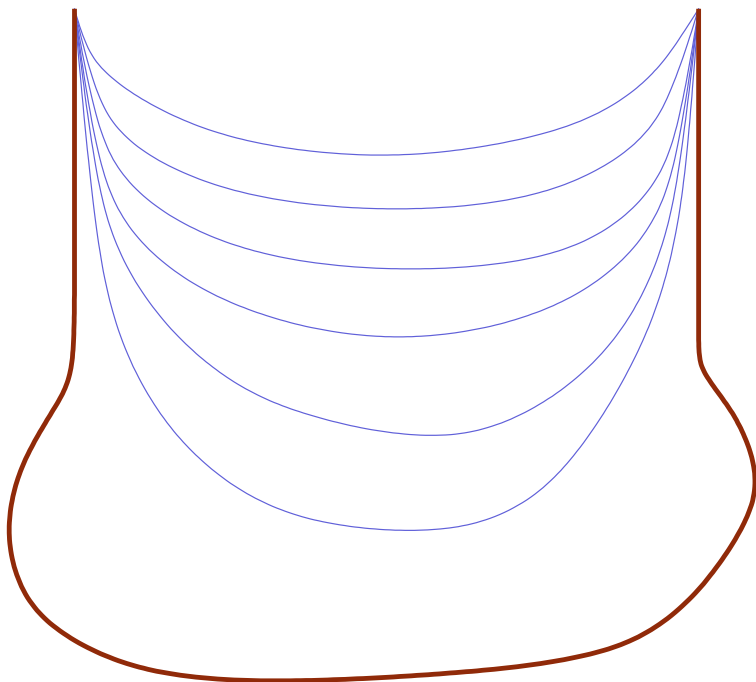
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



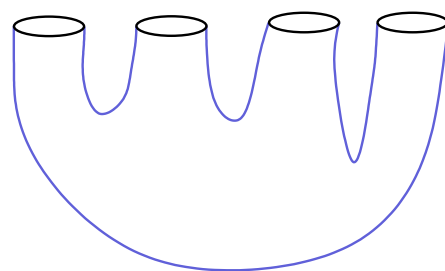


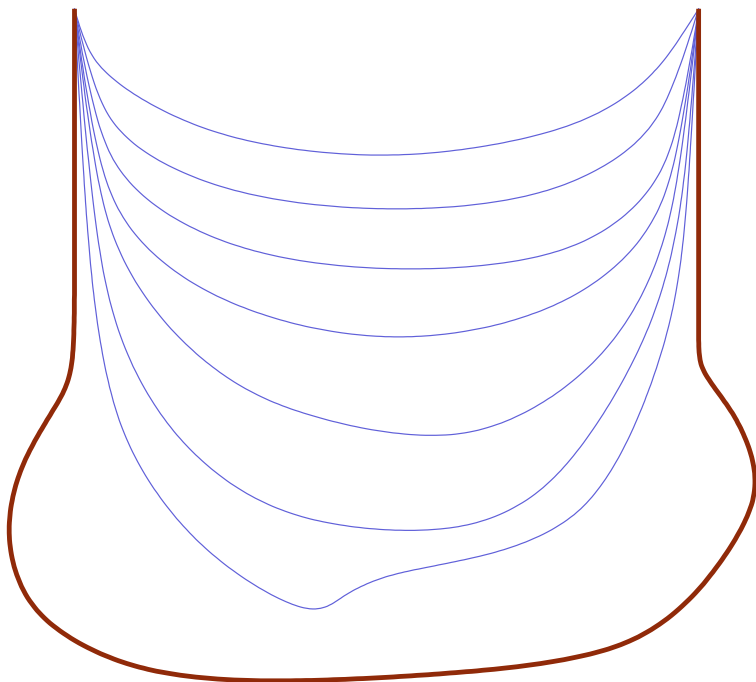
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



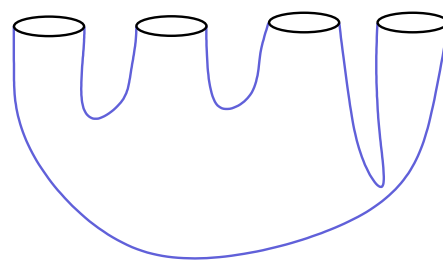


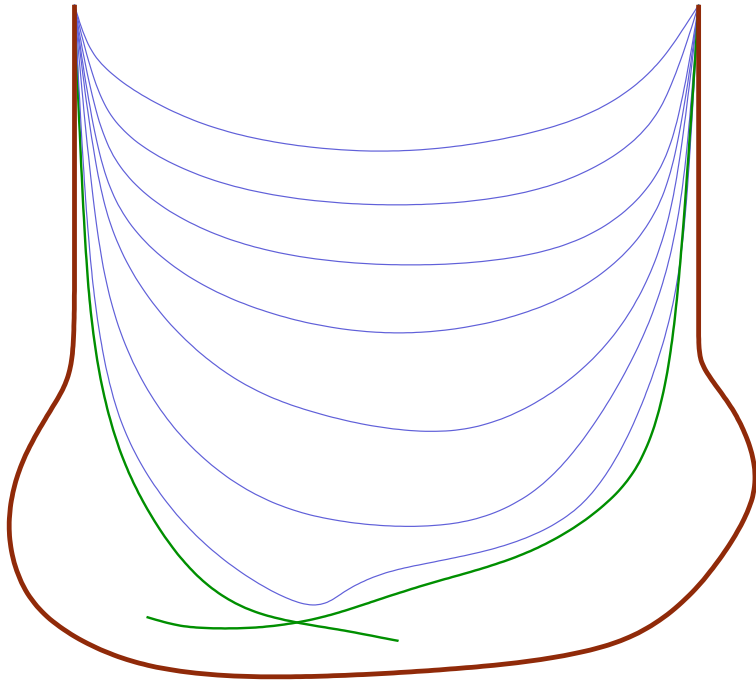
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



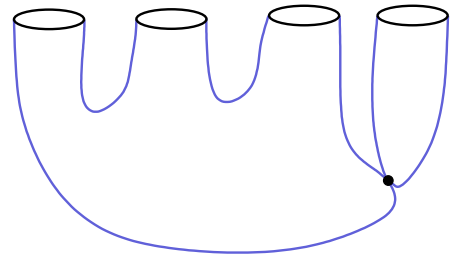


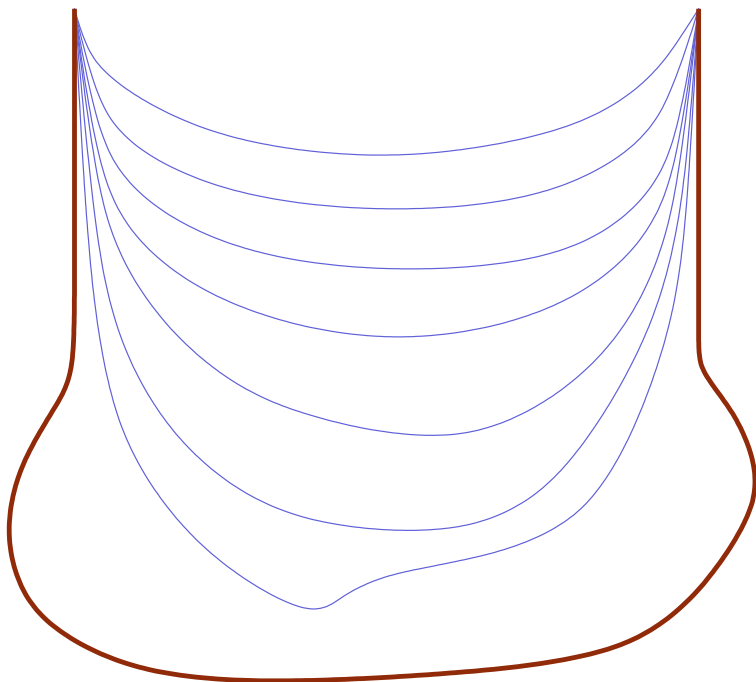
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



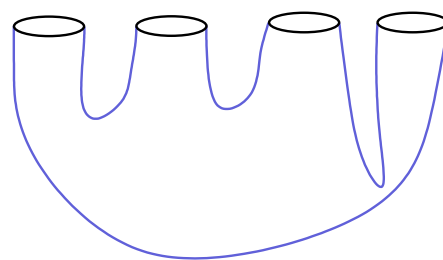


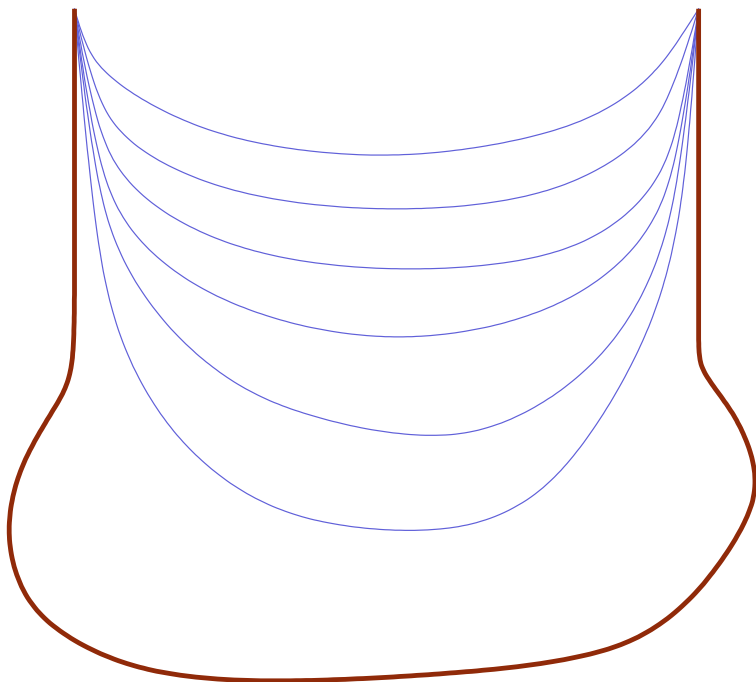
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



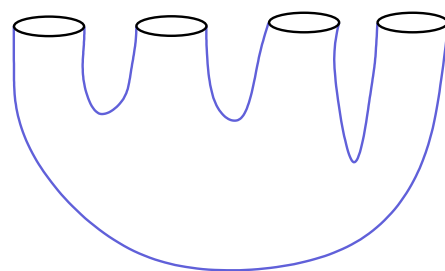


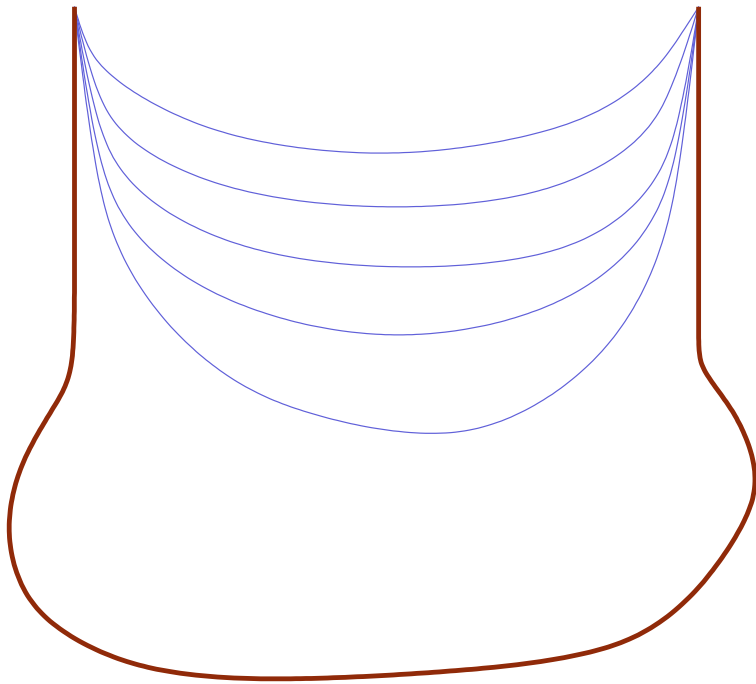
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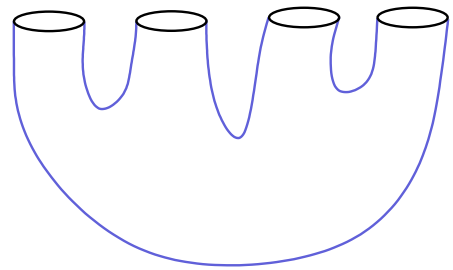


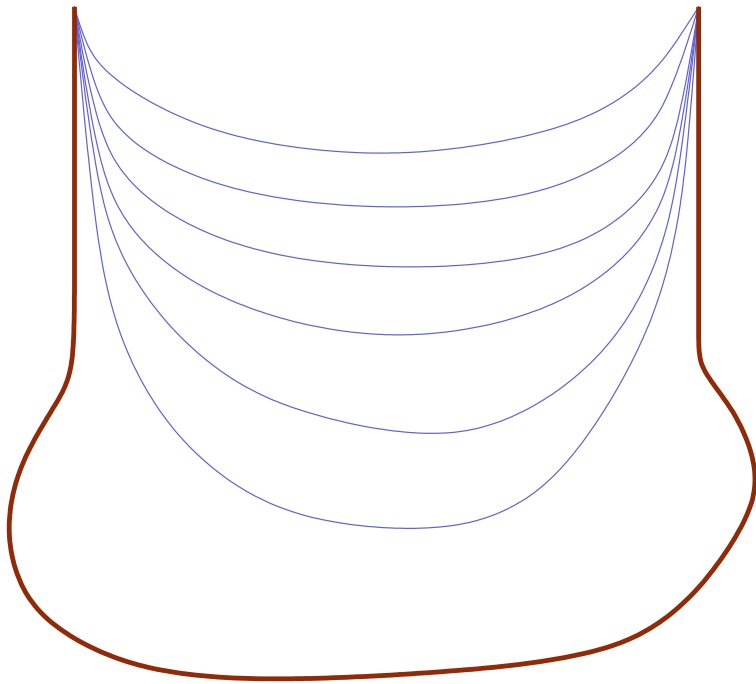
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



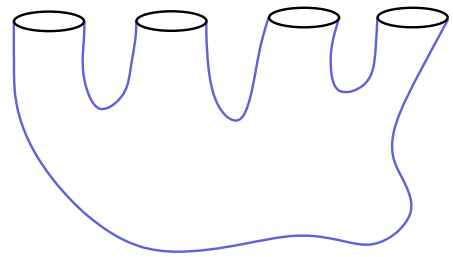


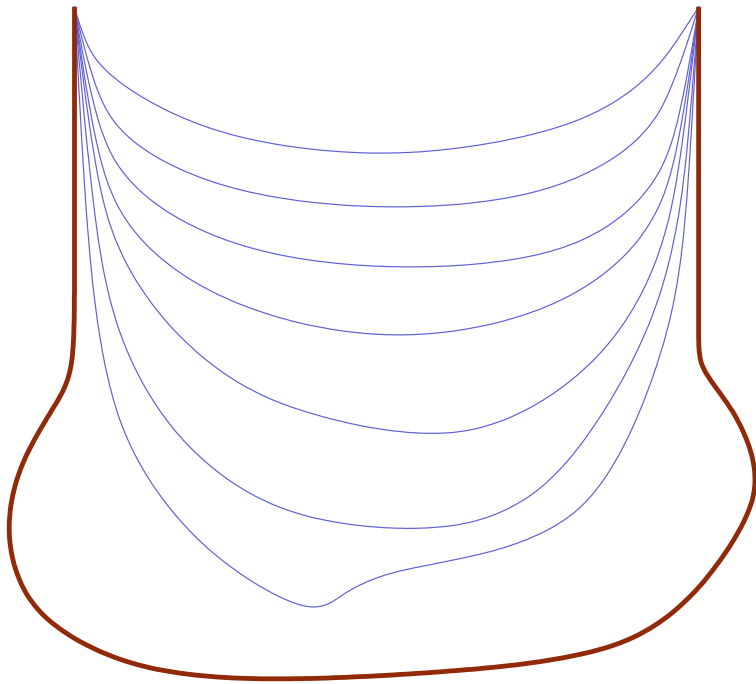
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



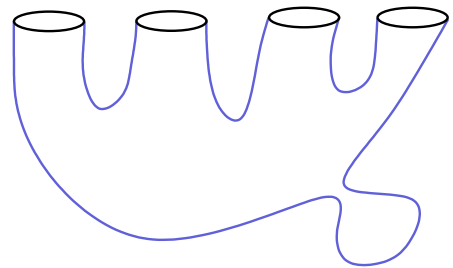


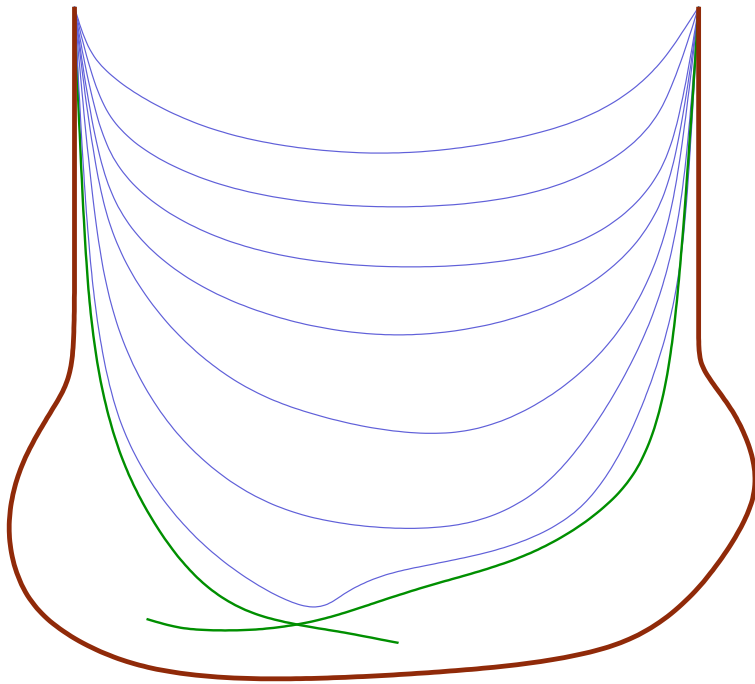
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



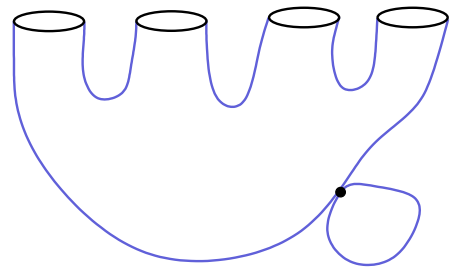


$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$

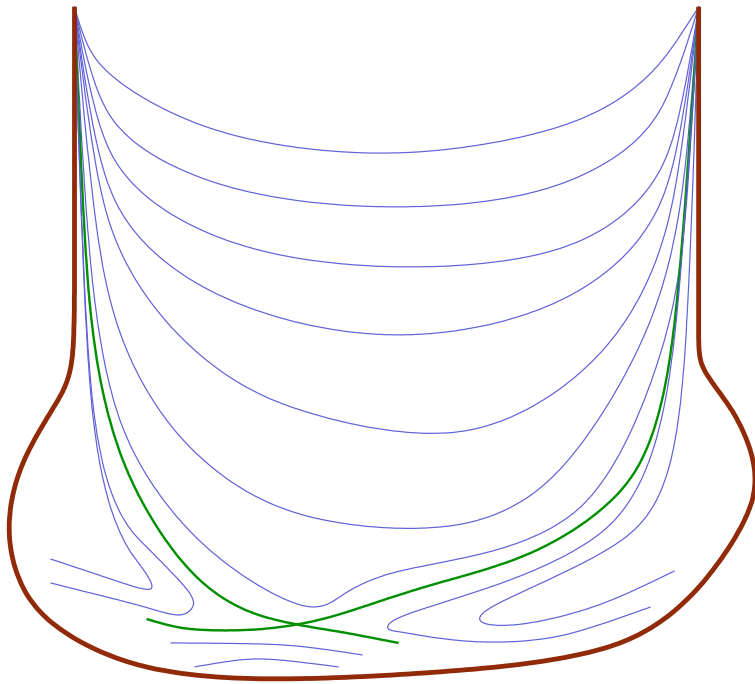




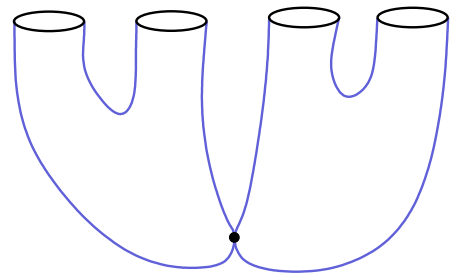
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$

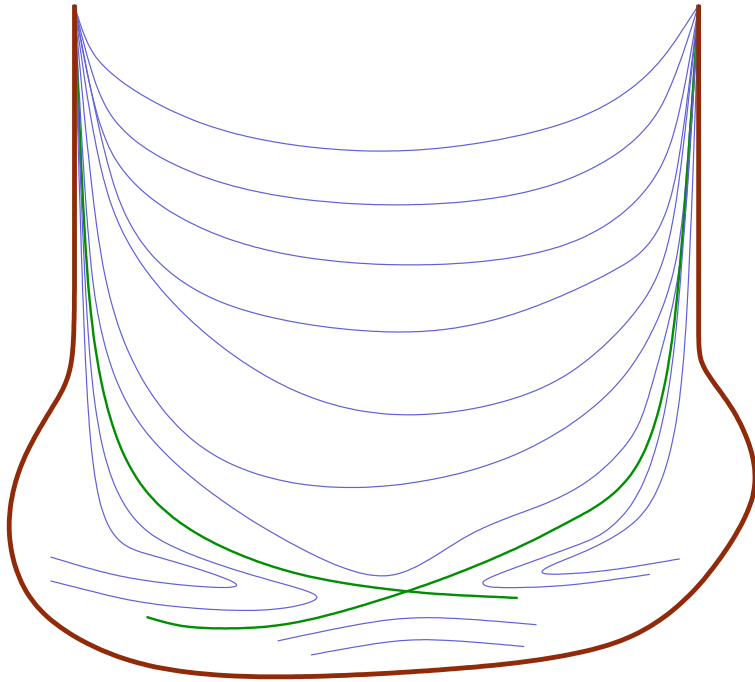


only if ω_{τ_0} not exact!

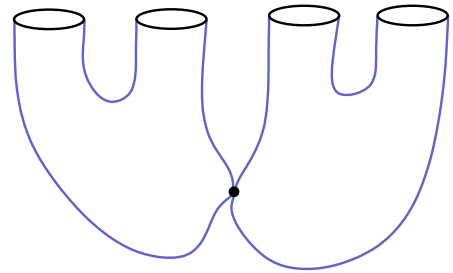


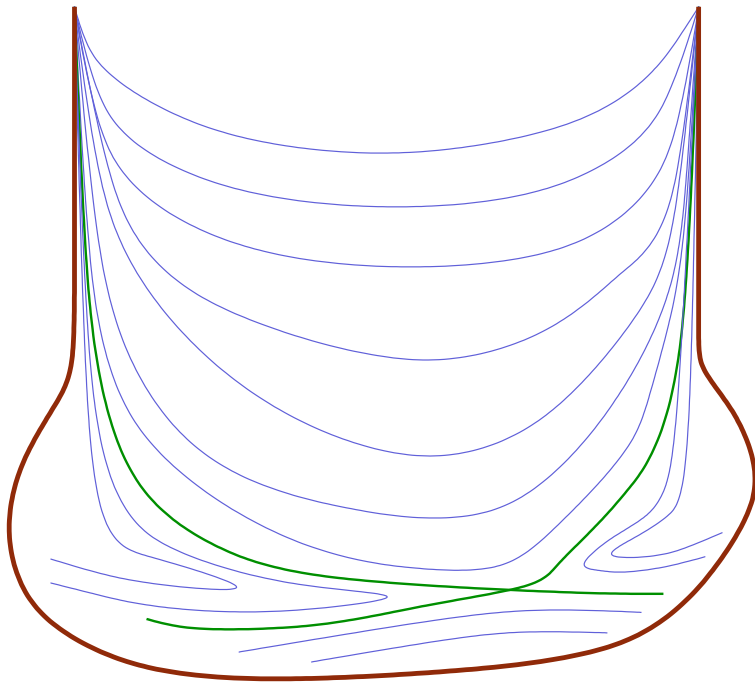
$(\widehat{W}, \widehat{\omega}_{\tau_0}, J_{\tau_0})$



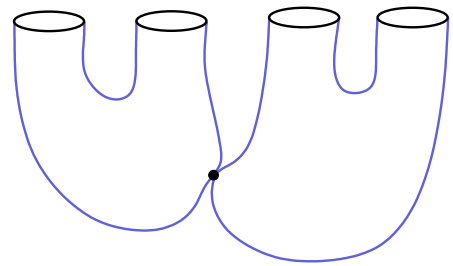


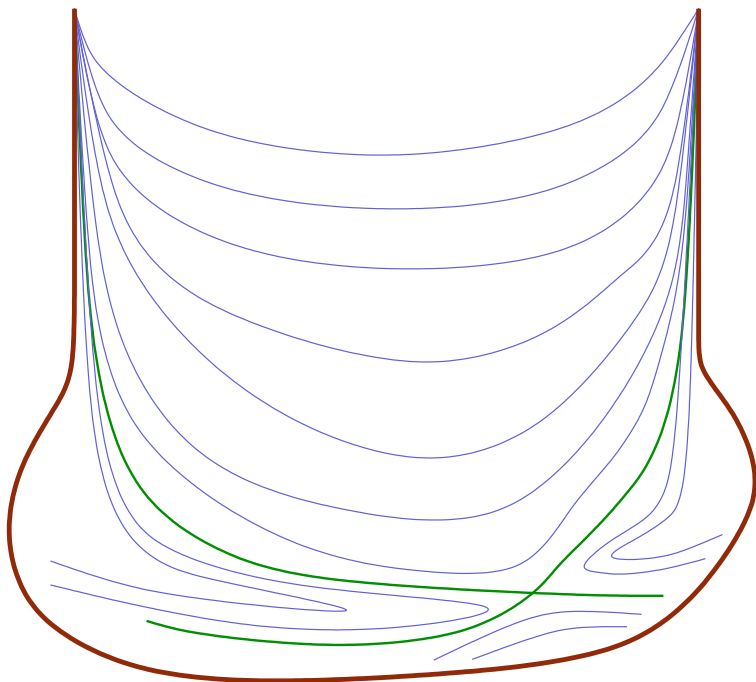
$(\widehat{W}, \widehat{\omega}_{\tau_1}, J_{\tau_1})$



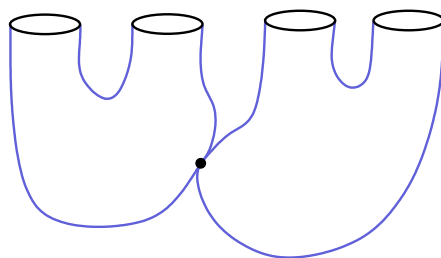


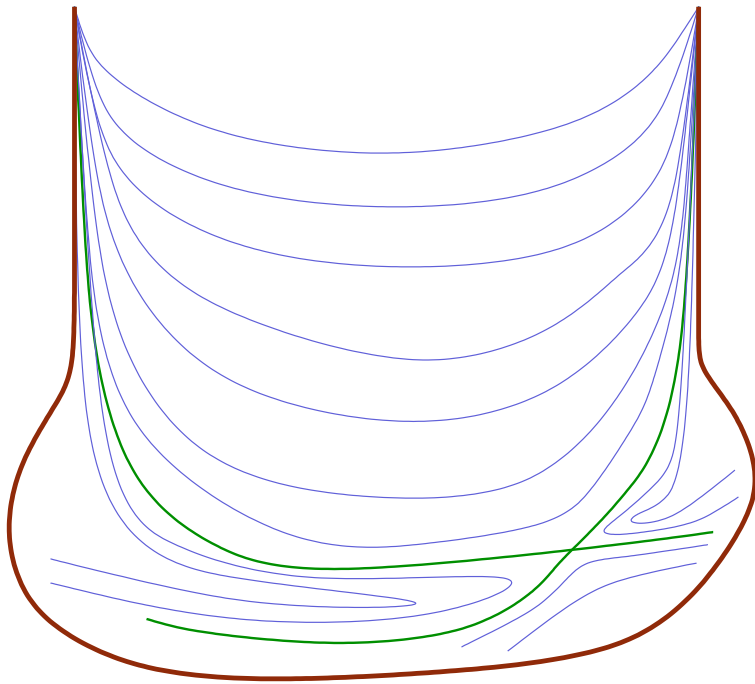
$(\widehat{W}, \widehat{\omega}_{\tau_2}, J_{\tau_2})$



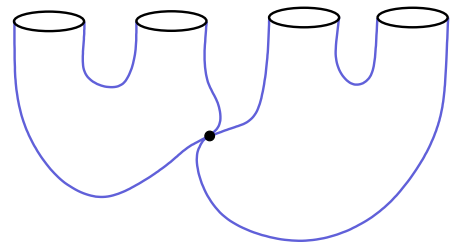


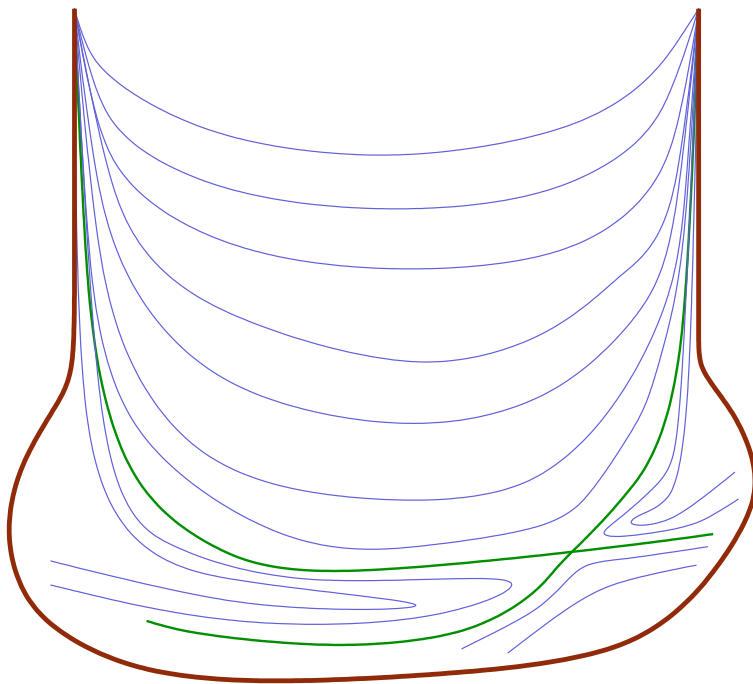
$(\widehat{W}, \widehat{\omega}_{\tau_3}, J_{\tau_3})$



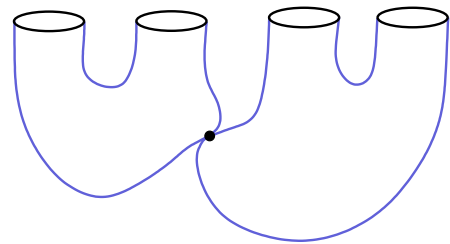


$(\widehat{W}, \widehat{\omega}_{\tau_4}, J_{\tau_4})$

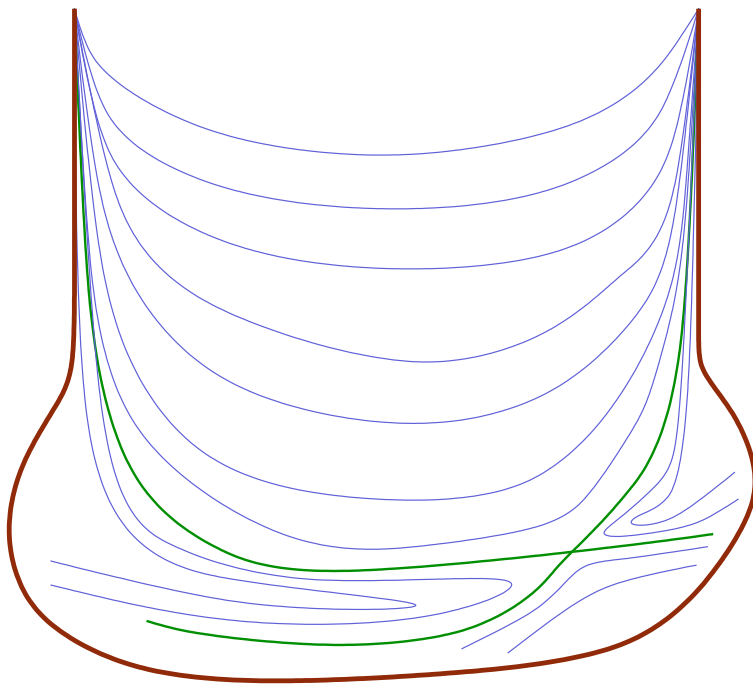




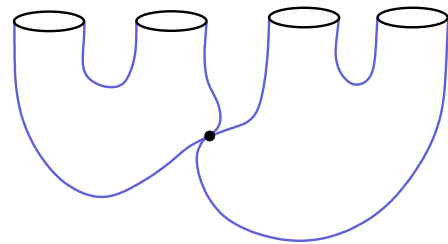
$$(\widehat{W}, \widehat{\omega}_{\tau_4}, J_{\tau_4})$$



Remark: This does *not* work with higher-genus open books. Curves have index $2 - 2g$.

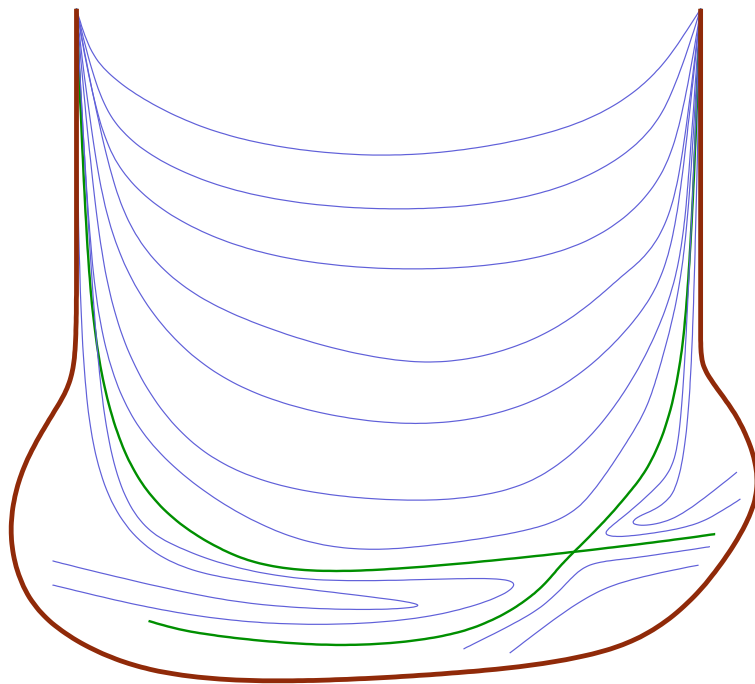


$(\widehat{W}, \widehat{\omega}_{\tau_4}, J_{\tau_4})$

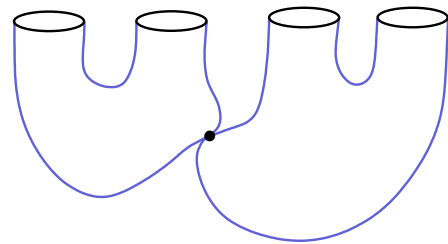


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Proof of main theorem:



$$(\widehat{W}, \widehat{\omega}_{\tau_4}, J_{\tau_4})$$

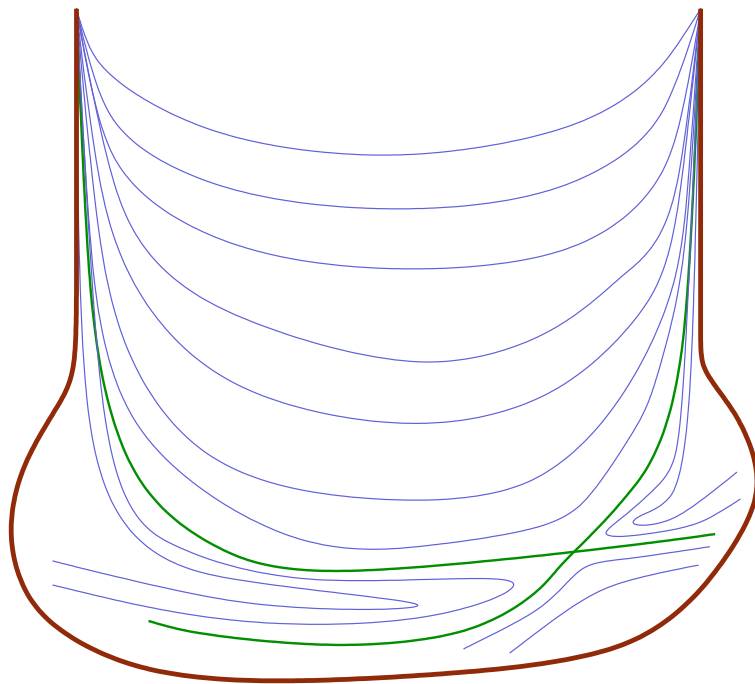


Remark: This does *not* work with higher-genus open books. Curves have index $2 - 2g$.

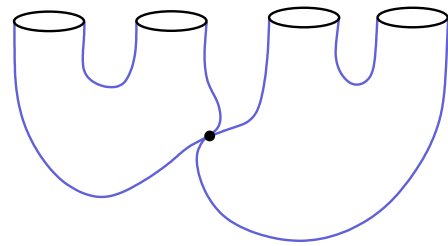
Proof of main theorem:

Symplectic deformation

\implies isotopy of Lefschetz fibrations



$(\widehat{W}, \widehat{\omega}_{\tau_4}, J_{\tau_4})$



Remark: This does *not* work with higher-genus open books. Curves have index $2 - 2g$.

Proof of main theorem:

Symplectic deformation

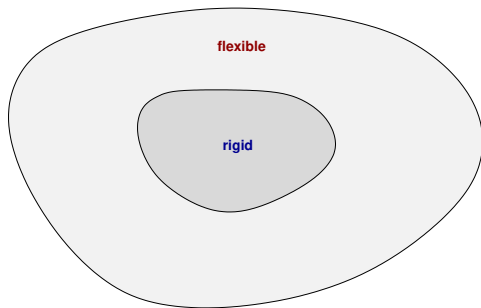
\implies isotopy of Lefschetz fibrations

\implies homotopy of Stein structures.

□

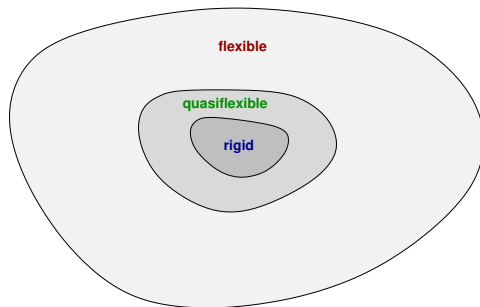
Conclusion

Even rigid structures can be...



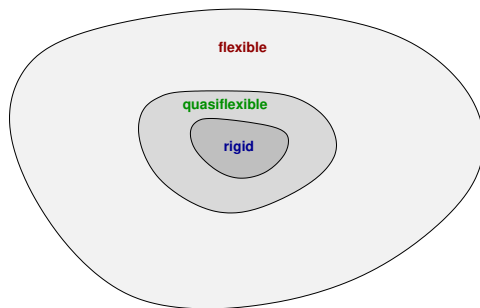
Conclusion

Even rigid structures can be... **somewhat flexible.**



Conclusion

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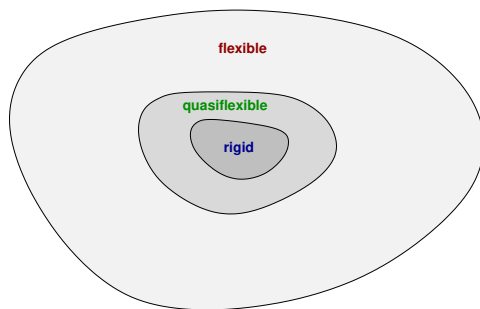


Some questions for the future

- Is there quasiflexibility in **higher dimensions**?

Conclusion

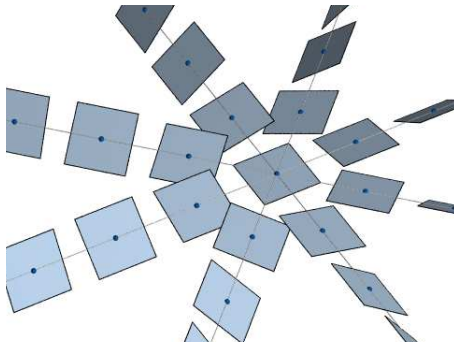
Even rigid structures can be... **somewhat flexible**.



Some questions for the future

- Is there quasiflexibility in **higher dimensions**?
- Is there a quasiflexible class of **contact structures** in dimension 3?
(*planar?*)

Thank you for your attention!



Pictures of contact structures by Patrick Massot:

https://www.math.u-psud.fr/~pmassot/exposition/gallerie_contact/